# Hybrid-Dynamic Ehrenfeucht-Fraïssé Games

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Ehrenfeucht-Fraïssé games provide means to characterize elementary equivalence for first-order logic, and by standard translation also for modal logics. We propose a novel generalization of Ehrenfeucht-Fraïssé games to hybrid-dynamic logics which is direct and fully modular: parameterized by the features of the hybrid language we wish to include, for instance, the modal and hybrid language operators as well as first-order existential quantification. We use these games to establish a new modular Fraïssé-Hintikka theorem for hybrid-dynamic propositional logic and its various fragments. We study the relationship between countable game equivalence (determined by countable Ehrenfeucht-Fraïssé games) and bisimulation (determined by countable back-and-forth systems). In general, the former turns out to be weaker than the latter, but under certain conditions on the language, the two coincide. As a corollary we obtain an analogue of the Hennessy-Milner theorem. We also prove that for reachable image-finite Kripke structures elementary equivalence implies isomorphism.

CCS Concepts: • Theory of computation → Modal and temporal logics; Logic and verification.

Additional Key Words and Phrases: hybrid logic, dynamic logic, Ehrenfeucht-Fraïssé game, back-and-forth system, algebraic specification

## 1 INTRODUCTION

Hybrid logics and, in particular, hybrid-dynamic logics, are expressive modal logics well-suited for describing behavioral dynamics: *if something holds at a certain state, then something else holds at some state accessible from it.* Hybrid dynamics logics have been applied to the specification and modelling of reactive and event/data-based systems (see, e.g., [14, 17, 19]). The expressivity of dynamic-propositional logic (DPL) extends beyond its hybrid counterpart at the expense of important logical properties such as compactness [18]. Lesser-known, perhaps, is the fact that hybrid-dynamic propositional logic (HDPL) is sufficiently expressive to describe finite models (see Example 2.5).

Ehrenfeucht-Fraïssé (EF) games characterize elementary equivalence in first-order logic [15]. In this paper, we propose a modular notion of EF games for HDPL and its fragments, designed to accommodate various forms of quantification encountered in modal logics. The advantages of modularity in the context of hybrid logics are thoroughly demonstrated in [5]. We apply this framework to establish a Fraïssé-Hintikka Theorem [15] for hybrid-dynamic logics and to study the relationship between countable game equivalence (determined by countable EF games),  $\omega$ -bisimulations and back-and-forth systems [3]. In an EF game, the players' moves correspond to various types of (hybrid) quantification, including possibility over structured actions, first-order quantification, and store, which names the current state. The mathematical structure supporting this formalization is the gameboard tree [13], which we extend with edge labels. The

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role of such trees is comparable to that of a chessboard in chess. Gameboard trees can also be seen as representing the quantifier ranks of sentences, as nodes correspond to signatures, and edges represent labeled extensions of signatures with variables.

In this paper, we examine both versions of EF games: the finite and the countably infinite. The winning strategies in finite EF games, played over gameboard trees, are precisely described by so-called *game sentences*, which are defined over such trees. In the literature, the result stating that a winning strategy in a finite EF game is exactly described by a game sentence is known as the Fraïssé-Hintikka Theorem (Theorem 3.6); it holds for all fragments of hybrid-dynamic propositional logic, including dynamic propositional logic. To the best of our knowledge, no proof of the Fraïssé-Hintikka Theorem for hybrid or dynamic logics appears in the existing literature. A direct consequence of this theorem is a characterization of hybrid-dynamic elementary equivalence in terms of EF games (Corollary 3.7), asserting that finite EF games yield an equivalence that aligns with elementary equivalence: pointed models cannot be distinguished by sentences. We further show that the equivalence induced by countably infinite EF games coincides with  $\omega$ -bisimilarity and, under certain conditions, with back-and-forth equivalence. As applications, we prove an analogue of the Hennessy–Milner theorem and show that, for rooted image-finite models, elementary equivalence coincides with isomorphism.

Several variations of EF games have been proposed in the literature for hybrid logics, but not for hybrid-dynamic logics. For example, EF games for hybrid temporal logic are introduced in [1], while EF games for hybrid computational tree logic are proposed in [16]. Notably, the characterizations of hybrid elementary equivalence in these works are established directly by induction on the complexity of hybrid sentences, rather than as consequences of a Fraïssé-Hintikka Theorem.

This work incorporates several features that shape its approach to EF games: (a) First, it is grounded in category theory, which provides a foundational framework for constructing EF games, including the notion of gameboard trees. In this setting, Spoiler/∀belard's moves are suitably restricted, enabling the definition of game sentences — formulas that precisely characterize the allowable moves in the game. These game sentences are then used to prove that elementary equivalence coincides with the existence of a winning strategy for Duplicator/∃loise. (b) Second, the use of gameboard trees enables a modular approach to EF games. By selectively adding or removing conditions — corresponding to the sentence operators under consideration — one can adapt the framework to specific logical fragments. This flexibility is particularly valuable in applications where the full expressive power of hybrid-dynamic logic is unnecessary, and where attention may instead be limited to a fragment such as hybrid propositional logic (HPL).

Other frameworks also support modular reasoning. For example, bisimulations — commonly regarded as the modal counterpart to EF games [20] — exhibit a modular structure. We show that  $\omega$ -bisimulations correspond to winning strategies for  $\exists$ loise in countably infinite EF games. In contrast, back-and-forth systems — typically seen as formalizations of  $\exists$ loise's strategy [3] — tend to be stronger. Their equivalence with EF games holds only when the logical fragment is closed under certain sentence operators. This suggests that the back-and-forth approach may implicitly assume the availability of these operators in the language, which could affect its adaptability across different logical fragments. Each approach has its own strengths and limitations, but a choice must ultimately be made based on the intended use and future development. In this context, our approach to EF games — grounded in gameboard trees and characterized by game sentences — offers a pathway toward mechanization and the development of tools tailored to specific logical fragments, especially in domains where limited expressiveness is both sufficient and desirable.

Structure of the paper. We first introduce the logical framework of Hybrid-Dynamic Propositional Logic (HDPL) in Section 2 as a family of languages parameterized by sentence constructors. In Section 3, we describe finite Ehrenfeucht-Fraïssé games for HDPL and its fragments and prove a general, modular Fraïssé-Hintikka theorem for characterizing

elementary equivalence. We move to infinite Ehrenfeucht-Fraïssé games in Section 4 and relate these games to  $\omega$ -bisimulations and back-and-forth systems; in particular, for image-finite models, we obtain a Hennessy-Milner for the quantifier-free fragment of HPL and we show that rooted, elementarily equivalent models are isomorphic. We conclude in Section 5.

# 2 HYBRID-DYNAMIC PROPOSITIONAL LOGIC (HDPL)

#### 2.1 Signatures

The signatures are of the form  $(\Sigma, \mathsf{Prop})$ , where  $\Sigma = (F, P)$  is a single-sorted first-order signature consisting of a set of constants F called nominals and a set of binary relation symbols P, and  $\mathsf{Prop}$  is a set of propositional symbols. We let  $\Delta$  range over signatures of the form  $(\Sigma, \mathsf{Prop})$  as described above. Similarly, for any index i, we let  $\Delta_i$  range over signatures of the form  $(\Sigma_i, \mathsf{Prop}_i)$ , where  $\Sigma_i$  is a single-sorted first-order signature of the form  $(F_i, P_i)$  defined similarly as above. A signature morphism  $\chi : \Delta_1 \to \Delta_2$  consists of a first-order signature morphism  $\chi : \Sigma_1 \to \Sigma_2$  and a function  $\chi : \mathsf{Prop}_1 \to \mathsf{Prop}_2$ . The *extension* of  $\Delta$  by a fresh nominal k is denoted  $\Delta[k]$  yielding the inclusion  $\Delta \hookrightarrow \Delta[k]$ . We denote by  $\mathsf{Sig}^{\mathsf{HDPL}}$  the category of HDPL signatures.

# 2.2 Models

The models defined over a signature  $\Delta$  are standard Kripke structures  $\mathfrak{M} = (W, M)$  such that:

- (1) W is a first-order structure over  $\Sigma$ . We denote by  $|\mathfrak{M}|$  the universe of W and we call the elements of  $|\mathfrak{M}|$  states, possible worlds or nodes. The accessibility relations consist of the interpretations of the binary relation symbols from P into W, that is,  $\lambda^W$  is an accessibility relation for each binary relation symbol  $\lambda \in P$ .
- (2)  $M: |\mathfrak{M}| \to |\mathsf{Mod}^{\mathsf{PL}}(\mathsf{Prop})|$  is a mapping from the set of states  $|\mathfrak{M}|$  to the class of propositional logic models  $|\mathsf{Mod}^{\mathsf{PL}}(\mathsf{Prop})|$ , i. e., subsets of propositional symbols.

We let  $\mathfrak{M}$  and  $\mathfrak{N}$  range over Kripke structures of the form (W, M) and (V, N), respectively. Similarly, for any index i we let  $\mathfrak{M}_i$  and  $\mathfrak{N}_i$  range over Kripke structures of the form  $(W_i, M_i)$  and  $(V_i, N_i)$ , respectively. A homomorphism  $h: \mathfrak{M} \to \mathfrak{N}$  between two Kripke structures  $\mathfrak{M}$  and  $\mathfrak{N}$  is a first-order homomorphism  $h: W \to V$  such that  $h(M(w)) \subseteq N(h(w))$  for all states  $w \in |\mathfrak{M}|$ .

FACT 2.1. For any signature  $\Delta$ , the  $\Delta$ -homomorphisms form a category  $\mathsf{Mod}^{\mathsf{HDPL}}(\Delta)$  under the obvious composition as many-sorted functions.

For any signature morphism  $\chi: \Delta_1 \to \Delta_2$  the reduct functor  $-|\chi: \mathsf{Mod}^{\mathsf{HDPL}}(\Delta_2) \to \mathsf{Mod}^{\mathsf{HDPL}}(\Delta_1)$  is defined as follows: The reduct  $\mathfrak{M}|\chi$  of the  $\Delta_2$ -model  $\mathfrak{M}$  is  $(W|\chi, M|\chi)$ , where  $W|\chi$  is the reduct of W across  $\chi: \Sigma_1 \to \Sigma_2$  in first-order logic, and  $(M|\chi)(w) = M(w)|\chi = \{p \in \mathsf{Prop}_1 \mid \chi(p) \in M(w)\}$  is the reduct of M(w) across  $\chi: \mathsf{Prop}_1 \to \mathsf{Prop}_2$  in propositional logic, for all states  $w \in |\mathfrak{M}|$ . The reduct  $h|\chi$  of a  $\Delta_2$ -homomorphism  $h: \mathfrak{M} \to \mathfrak{N}$  is the first-order homomorphism  $h|\chi: W|\chi \to V|\chi$ . Since  $h(M(w)) \subseteq N(w)$  for all states  $w \in |\mathfrak{M}|$ , we get  $(h|\chi)(M(w)|\chi) \subseteq N(w)|\chi$  for all states  $w \in |\mathfrak{M}| = |\mathfrak{M}|\chi|$ , which means that  $h|\chi$  is well-defined. If  $\chi: \Delta_1 \to \Delta_2$  is an inclusion, we also write  $\mathfrak{M}|\Delta_1$  for  $\mathfrak{M}|\chi$ .

FACT 2.2.  $\mathsf{Mod}^{\mathsf{HDPL}}: \mathsf{Sig}^{\mathsf{HDPL}} \to \mathbb{C}\mathsf{at}^{\mathsf{op}}$  is a functor with  $\mathsf{Mod}^{\mathsf{HDPL}}(\chi)(h) = h|\chi$  for each signature morphism  $\chi: \Delta_1 \to \Delta_2$  and each  $\Delta_2$ -homomorphism h, where  $\mathbb{C}\mathsf{at}$  is the category of all categories.

#### 2.3 Actions

The set of actions  $\mathcal{A}^{\mathsf{HDPL}}(\Delta)$  over a signature  $\Delta$  is defined by the following grammar:

$$\mathfrak{a} := \lambda \mid \mathfrak{a} \cup \mathfrak{a} \mid \mathfrak{a} \circ \mathfrak{a} \mid \mathfrak{a}^*$$
,

where  $\lambda$  is a binary relation on nominals. Actions are interpreted in Kripke structures (W, M) as accessibility relations between possible worlds. This is done by extending the interpretation of binary relation symbols on nominals:

- (1)  $\lambda^{\mathfrak{M}} = \lambda^{W}$  for all binary relations  $\lambda$  in  $\Delta$ ,
- (2)  $(\mathfrak{a}_1 \cup \mathfrak{a}_2)^{\mathfrak{M}} = \mathfrak{a}_1^{\mathfrak{M}} \cup \mathfrak{a}_2^{\mathfrak{M}}$  (union),
- (3)  $(\mathfrak{a}_1 \, \mathfrak{s} \, \mathfrak{a}_2)^{\mathfrak{M}} = \mathfrak{a}_1^{\mathfrak{M}} \, \mathfrak{s} \, \mathfrak{a}_2^{\mathfrak{M}}$  (diagrammatic composition of relations), and
- (4)  $(\mathfrak{a}^*)^{\mathfrak{M}} = (\mathfrak{a}^{\mathfrak{M}})^*$  (reflexive & transitive closure).

#### 2.4 Sentences

Let  $\{v_n \mid n \in \mathbb{N}\}$  be a set of variable names. A variable for a signature  $\Delta$  is a pair  $x = \langle v_n, \Delta \rangle$ , where  $v_n$  is a variable name. Notice that all variables  $x = \langle v_n, \Delta \rangle$  are different from all symbols in  $\Delta$ . The translation of x along a signature morphism  $\chi : \Delta \to \Delta'$  is  $x' = \langle v_n, \Delta' \rangle$ . The set of sentences Sen<sup>HDPL</sup>( $\Delta$ ) over a signature  $\Delta$  is defined by the following grammar:

$$\phi ::= p \mid k \mid \land \Phi \mid \neg \phi \mid \langle \mathfrak{a} \rangle \phi \mid @_k \phi \mid \downarrow x \cdot \phi_x \mid \exists x \cdot \phi_x ,$$

where p is a propositional symbol, k is a nominal,  $\Phi$  is a finite set of sentences over  $\Delta$ , x is a variable for  $\Delta$ ,  $\mathfrak{a}$  is an action over  $\Delta$ , and  $\phi_x \in \mathsf{Sen}^\mathsf{HDPL}(\Delta[x])$ . The sentence  $\langle \mathfrak{a} \rangle \phi$  is read as " $\phi$  holds after  $\mathfrak{a}$ " (possibility),  $@_k \phi$  as " $\phi$  holds at state k" (retrieve), and  $\downarrow x \cdot \phi_x$  as " $\phi_x$  holds with the current state bound to x" (store). We will use the usual abbreviations  $\vee \Phi$  for  $\neg(\wedge_{\phi \in \Phi} \neg \phi)$ ,  $[\mathfrak{a}] \phi$  for  $\neg \langle \mathfrak{a} \rangle \neg \phi$ , and  $\forall x \cdot \phi_x$  for  $\neg \exists x \cdot \neg \phi_x$ . Each signature morphism  $\chi : \Delta_1 \to \Delta_2$  induces a sentence translation  $\chi : \mathsf{Sen}(\Delta_1) \to \mathsf{Sen}(\Delta_2)$  that replaces, in an inductive manner, in any  $\Delta_1$ -sentence  $\phi$  each symbol from  $\Delta_1$  with a symbol from  $\Delta_2$  according to  $\chi : \Delta_1 \to \Delta_2$ .

It is worth noting that the translation of a quantified sentence  $\exists x \cdot \phi_x \in \text{Sen}(\Delta_1)$ , where  $x = \langle v_n, \Delta_1 \rangle$ , along  $\chi : \Delta_1 \to \Delta_2$  is  $\exists x' \cdot \chi'(\phi_x)$ , where  $x' = \langle v_n, \Delta_2 \rangle$  and  $\chi' : \Delta_1[x] \to \Delta_2[x']$  is the extension of  $\chi : \Delta_1 \to \Delta_2$  which maps x to its translation x'.

$$\phi_{x} \cdots \Delta_{1}[x] \xrightarrow{\chi'} \Delta_{2}[x'] \cdots \chi'(\phi_{x})$$

$$\uparrow \qquad \qquad \uparrow$$

$$\exists x \cdot \phi_{x} \cdots \Delta_{1} \xrightarrow{\chi} \Delta_{2} \cdots \exists x' \cdot \chi'(\phi_{x})$$

FACT 2.3.  $Sen^{HDPL} : Sig^{HDPL} \rightarrow \mathbb{S}et$  is a functor, where  $\mathbb{S}et$  is the category of all sets.

This approach proves useful in preventing clashes between variables and constants within a given signature. Furthermore, substitutions can be defined cleanly, avoiding the need for side conditions. When there is no danger of confusion (e.g., a variable name is among the elements of a signature), we identify a variable only by its name. This means that signature inclusions  $\Delta_1 \subseteq \Delta_2$  determine inclusions of sets of sentences  $Sen(\Delta_1) \subseteq Sen(\Delta_2)$ .

#### 2.5 Local satisfaction relation

The local satisfaction relation of a sentence  $\phi$  over a model  $\mathfrak{M}=(W,M)$  over a signature  $\Delta$  and a world  $w\in |\mathfrak{M}|$  is defined by induction on the structure of the sentence:

•  $(\mathfrak{M}, w) \models p$  if  $M(w) \models p$  in propositional logic, that is,  $p \in M(w)$ ;

- $(\mathfrak{M}, w) \models k \text{ if } w = k^{\mathfrak{M}}$
- $(\mathfrak{M}, w) \models \bigwedge \Phi \text{ if } (\mathfrak{M}, w) \models \phi \text{ for all } \phi \in \Phi;$
- $(\mathfrak{M}, w) \models \neg \phi \text{ if } (\mathfrak{M}, w) \not\models \phi;$
- $(\mathfrak{M}, w) \models @_k \phi \text{ if } (\mathfrak{M}, k^{\mathfrak{M}}) \models \phi;$
- $(\mathfrak{M}, w) \models \langle \mathfrak{a} \rangle \phi$  if  $(\mathfrak{M}, v) \models \phi$  for some  $v \in \mathfrak{a}^{\mathfrak{M}}(w) := \{ w' \in |\mathfrak{M}| \mid (w, w') \in \mathfrak{a}^{\mathfrak{M}} \};$
- $\bullet \ (\mathfrak{M},w)\models \mathop{\downarrow}\! x\cdot \phi_x \text{ if } (\mathfrak{M}^{x\leftarrow w},w)\models \phi_x,$

where  $\mathfrak{M}^{x \leftarrow w}$  is the unique expansion of  $\mathfrak{M}$  to  $\Delta[x]$  interpreting x as w;

•  $(\mathfrak{M}, w) \models \exists x \cdot \phi_x \text{ if } (\mathfrak{M}^{x \leftarrow v}, w) \models \phi_x \text{ for some } v \in |\mathfrak{M}|.$ 

We call the pair  $(\mathfrak{M}, w)$  a pointed model, where w is the current (or initial) state.

Theorem 2.4 (Local satisfaction condition). For all signature morphisms  $\chi: \Delta_1 \to \Delta_2$ , all  $\Delta_2$ -models  $\mathfrak{M}$ , all states  $w \in |\mathfrak{M}|$ , all  $\Delta_1$ -sentences  $\phi$ , we have

$$(\mathfrak{M}, w) \models \chi(\phi) iff(\mathfrak{M}|\chi, w) \models \phi$$
.

Theorem 2.4 shows that HDPL is a stratified institution according to the definitions given in [8, 10]. For a proof of the local satisfaction condition one may refer to [7].

As an example of the expressivity of HDPL we outline a method for characterizing finite linear orderings:

Example 2.5. Let  $\Delta$  be a signature with two nominals  $k_1, k_2$  and one binary relation  $\lambda$ . Here,  $k_1$  and  $k_2$  represent the minimal and maximal elements, respectively, while  $\lambda$  represents the immediate successor relation in a discrete linear ordering:

- Let  $\phi_1 := (\exists x! \cdot @_{k_1} \langle \lambda \rangle x) \land (\forall y \cdot \neg @_y \langle \lambda \rangle k_1)$ , where  $\exists x! \cdot \gamma := \exists x \cdot \gamma \land \forall y \cdot \gamma [y/x] \rightarrow @_x y$ , indicating that there exists a unique x such that  $\gamma \in \text{Sen}(\Delta[x])$  is satisfied. Notice that  $\phi_1$  asserts that  $k_1$  has a unique successor and no predecessor, which in the context where all elements are connected by finite paths (see the definition of  $\phi_4$ ) means that  $k_1$  is the minimal element.
- Let  $\phi_2 := (\exists x! \cdot @_x \langle \lambda \rangle k_2) \wedge (\forall y \cdot \neg @_{k_2} \langle \lambda \rangle y)$ , which states that  $k_2$  has a unique predecessor and a no successor, which in this context means that  $k_2$  is the maximal element.
- Let  $\phi_3 := \forall x \cdot \neg @_x k_1 \wedge \neg @_x k_2 \rightarrow (\exists y! \cdot @_y \langle \lambda \rangle x) \wedge (\exists z! \cdot @_x \langle \lambda \rangle z)$ , which asserts that each element x, not being the minimum nor maximum, has a unique predecessor and successor.
- Let  $\phi_4 := \forall x, y \cdot @_x \langle \lambda^* \rangle y \vee @_y \langle \lambda^* \rangle x$ , which expresses that any elements x and y are connected by a finite path of edges labeled  $\lambda$ .

Therefore, the sentence  $\phi := \phi_1 \wedge \cdots \wedge \phi_4$  has only finite models.

# 2.6 Logical framework and related concepts

The logical framework in which the results will be developed in this paper is an arbitrary fragment  $\mathcal{L} = (Sig^{HDPL}, Sen^{\mathcal{L}}, Mod^{HDPL}, \models)$  of HDPL which is closed under Boolean connectives. This means that  $\mathcal{L}$  is obtained from HDPL by discarding

- some constructors for actions from the grammar which defines actions in HDPL, and/or
- some constructors for sentences from the grammar which defines sentences in HDPL.

For example, one can discard all action constructors and develop results over hybrid propositional logic (HPL); or one can work with the quantifier-free version of HDPL; or one can discard retrieve, store, and existential quantification,

and work with dynamic multi-modal propositional logic, DPL. For the sake of simplicity, we will drop the superscripts  $\mathcal{L}$  and HDPL from  $\mathcal{L} = (Sig^{HDPL}, Sen^{\mathcal{L}}, Mod^{HDPL}, \models)$  when there is no danger of confusion.

We make the following notational conventions:

- Let  $O \subseteq \{\diamondsuit, @, \downarrow, \exists\}$  be the subset of the sentence constructors which belong to  $\mathcal{L}^{1}$ .
- Let  $\operatorname{\mathsf{Mod}}_p(\Delta) = \{(\mathfrak{M}, w) \mid \mathfrak{M} \in |\operatorname{\mathsf{Mod}}(\Delta)| \text{ and } w \in |\mathfrak{M}|\}$  be the class of pointed  $\Delta$ -models.
- Let  $\mathsf{Mod}_p(\Delta, \phi) = \{(\mathfrak{M}, w) \in \mathsf{Mod}_p(\Delta) \mid (\mathfrak{M}, w) \models \phi\}$  be the class of pointed  $\Delta$ -models which satisfy a sentence  $\phi$ .
- Let  $\operatorname{Sen}_b : \operatorname{Sig} \to \mathbb{S}$ et be the subfunctor of  $\operatorname{Sen} : \operatorname{Sig} \to \mathbb{S}$ et which maps each signature  $\Delta = (\Sigma, \operatorname{Prop})$  to the set of basic sentences  $F \cup \operatorname{Prop}$ .

*Definition 2.6 (Elementary equivalence).* Let  $\Delta$  be a signature.

- Two pointed  $\Delta$ -models  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  are  $\mathcal{L}$ -elementarily equivalent, in symbols,  $(\mathfrak{M}, w) \equiv^{\mathcal{L}} (\mathfrak{N}, v)$ , when  $(\mathfrak{M}, w) \models \phi$  iff  $(\mathfrak{N}, v) \models \phi$ , for all  $\Delta$ -sentences  $\phi \in \operatorname{Sen}^{\mathcal{L}}(\Delta)$ .
- Two  $\Delta$ -sentences  $\phi_1$  and  $\phi_2$  are semantically equivalent if they are satisfied by the same pointed models, that is,  $\mathsf{Mod}_{\mathcal{P}}(\Delta,\phi_1) = \mathsf{Mod}_{\mathcal{P}}(\Delta,\phi_2)$ .

When there is no danger of confusion, we drop  $\mathcal{L}$  from the above notations.

#### 3 FINITE EHRENFEUCHT-FRAÏSSÉ GAMES

We propose a notion of EF game for hybrid-dynamic propositional logic and its fragments by generalizing in a non-trivial way the notion of EF game from first-order logic [15]. In this section, we are interested in characterizing elementary equivalence of pointed models in terms of EF games.

### 3.1 Gameboard trees

The EF games proposed in this paper are played on a gameboard tree between  $\forall$ belard and  $\exists$ loise exactly like the EF games defined in [13]. The nodes are labeled by signatures, while the edges are labeled by sentence operators and are uniquely identified by their source and label. Labels are introduced to account for moves in games corresponding to various types of quantification used in defining the language of HDPL (e.g., possibility of structured actions, store, or first-order quantification). The edges of the gameboard trees defined in [13] are unlabeled, since that work considers only one type of quantification — namely, first-order quantification. There are four types of edges classified by their label, which are depicted in Figure 1. Each type of edge is discarded from the gameboard tree if it is not included in the language fragment  $\mathcal L$  of discourse.

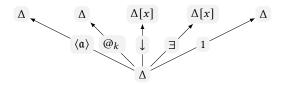


Fig. 1. Gameboard tree

 $<sup>^1 \</sup>diamondsuit \in O$  means that  $\mathcal L$  is closed under possibility over actions, but no assumption is made concerning the existence of action constructors. One or more constructors for actions can be discarded from  $\mathcal L$ .

- $\diamond \in O$ : The edge  $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta$  connects two distinct nodes that are both labeled by the same signature  $\Delta$ , where  $\mathfrak{a}$  is an action. It may be regarded as a pair consisting of the identity signature morphism  $1_{\Delta} : \Delta \to \Delta$  and the modal operator  $\langle \mathfrak{a} \rangle$ .
- $@ \in O$ : The edge  $\Delta \xrightarrow{@_k} \Delta$  connects distinct nodes that are labeled by the same signature  $\Delta$ , where k is a nominal. It may be regarded as a pair consisting of the identity signature morphism  $1_\Delta : \Delta \to \Delta$  and the operator retrieve  $@_k$ .
- $\downarrow \in O$ : The edge  $\Delta \xrightarrow{\downarrow} \Delta[x]$  connects distinct nodes labeled by the signatures  $\Delta$  and  $\Delta[x]$ , where  $x = \langle v_0, \Delta \rangle$  is a variable for  $\Delta$ . It may be regarded as a pair consisting of a signature inclusion  $\Delta \longrightarrow \Delta[x]$  and the operator store  $\rfloor x$ .
- $\exists \in O$ : The edge  $\Delta \xrightarrow{\exists} \Delta[x]$  connects distinct nodes labeled by the signatures  $\Delta$  and  $\Delta[x]$ , where  $x = \langle v_0, \Delta \rangle$  is a variable for  $\Delta$ . It may be regarded as a pair consisting of a signature inclusion  $\Delta \longrightarrow \Delta[x]$  and the first-order quantifier  $\exists x$ .
- idle: The edge  $\Delta \xrightarrow{1} \Delta$  connects distinct nodes that are labeled by the same signature  $\Delta$ . It may be regarded as the identity signature morphism  $1_{\Delta} : \Delta \to \Delta$ . The idle edge serves to construct complex gameboard trees from simpler components and to define game sentences that represent conjunctions.

If  $\mathcal{L}$  is closed under the possibility over actions, which in turn are not restricted, the number of edges from a given finite signature is infinite. In our approach we restrict  $\forall$ belard's choices to a finite set by playing the game on finite gameboard trees. If one discards the action operators, then the game can be played on complete gameboard trees which are finite provided that the root signature is finite.<sup>2</sup> In this case,  $\forall$ belard's choices are not restricted in any way and the game is similar to the classical one.

## 3.2 Ehrenfeucht-Fraïssé games

The game starts with two pointed models  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  defined over the same signature  $\Delta$ , and a gameboard tree tr with  $root(tr) = \Delta$ .  $\exists$  loise loses if the following  $game\ property$  is not satisfied:

$$(\mathfrak{M}, w) \models \phi \text{ iff } (\mathfrak{N}, v) \models \phi \text{ for all basic sentences } \phi \in \operatorname{Sen}_b(\Delta).$$

Otherwise, the game can continue and  $\forall$ belard can move one of the pointed models along an edge of the gameboard tree. Without loss of generality, we assume that  $\forall$ belard picks up the first pointed model  $(\mathfrak{M}, w)$ .

 $\diamond \in O$ : A move along  $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta$  means that the next state  $w_1$  chosen by  $\forall$ belard is accessible from w via  $\mathfrak{a}^{\mathfrak{M}}$ , his new pointed model becoming  $(\mathfrak{M}, w_1)$  with  $w \mathfrak{a}^{\mathfrak{M}} w_1$ .  $\exists$ loise needs to find a state  $v_1$  accessible from v via  $\mathfrak{a}^{\mathfrak{M}}$  such that for her resulting pointed model  $(\mathfrak{N}, v_1)$  the game property holds again.

 $@ \in O$ : A move along an edge  $\Delta \xrightarrow{@_k} \Delta$ , where k is a nominal in  $\Delta$ , means that  $\forall$ belard changes the current state w to  $k^{\mathfrak{M}}$ . The only possible choice for  $\exists$ loise is  $(\mathfrak{N}, k^{\mathfrak{N}})$ . The game continues with  $(\mathfrak{M}, k^{\mathfrak{M}})$  and  $(\mathfrak{N}, k^{\mathfrak{N}})$  if the

<sup>&</sup>lt;sup>2</sup>By a complete gameboard tree, we mean a gameboard tree that explores all possible moves, each labeled by a sentence operator, such that all subtrees rooted at its children have equal height.

game property holds again.

 $\downarrow \in O$ : A move along  $\Delta \xrightarrow{\downarrow} \Delta[x]$  means that  $\forall$ belard names the current state x, turning  $(\mathfrak{M}, w)$  into  $(\mathfrak{M}^{x \leftarrow w}, w)$ .  $\exists$ loise can only name her current state x, changing  $(\mathfrak{N}, v)$  into  $(\mathfrak{N}^{x \leftarrow v}, v)$ . The game continues if the game property holds for these new pointed models.

$$\begin{array}{cccc} (\mathfrak{M},w) & & \downarrow & & (\mathfrak{M}^{x\leftarrow w},w) \\ & \Delta & & & & \downarrow & \\ (\mathfrak{N},v) & & & & & & (\mathfrak{M}^{x\leftarrow v},v) \end{array}$$

 $\exists \in O$ : A move along  $\Delta \xrightarrow{\exists} \Delta[x]$  means that  $\forall$ belard names x a new arbitrary state  $w_1 \in |\mathfrak{M}|$  without changing his current state. His pointed model becomes  $(\mathfrak{M}^{x \leftarrow w_1}, w)$ .  $\exists$ loise needs to match  $\forall$ belard's choice by naming x a state  $v_1 \in |\mathfrak{N}|$ . The game continues with the new pointed models  $(\mathfrak{M}^{x \leftarrow w_1}, w)$  and  $(\mathfrak{N}^{x \leftarrow v_1}, v)$  if the game property holds again.

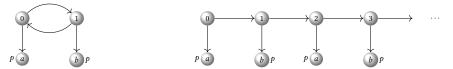
$$\begin{array}{cccc} (\mathfrak{M},w) & & \exists & & (\mathfrak{M}^{x\leftarrow w_1},w) \\ & \Delta & & & \exists & & \Delta[x] & \\ & & & & (\mathfrak{R}^{x\leftarrow v_1},v) & & \end{array}$$

**idle:** A move along  $\Delta \xrightarrow{1} \Delta$  does not change the pointed models. (These moves are needed for modularity and their role will be clear after reading the proof of Theorem 3.6(3)).

$$\begin{array}{ccc} (\mathfrak{M},w) & & & (\mathfrak{M},w) \\ & \Delta & & & 1 & & \Delta \\ & (\mathfrak{N},v) & & & & (\mathfrak{N},v) \end{array}$$

 $\exists$ loise loses the game if the game property is not satisfied by the current pair of pointed models;  $\exists$ loise wins the game if she can match any move made by  $\forall$ belard such that the game property is satisfied. We write  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$  if  $\exists$ loise has a winning strategy for all hybrid-dynamic EF game played on the gameboard tree tr. Notice that if  $\exists$ loise has a winning strategy over a gameboard tree tr, then she has a winning strategy over any gameboard tree tr' included in tr. Therefore, in HPL, one can work only with complete gameboard trees, since the number of binary relations of a finite signature is obviously finite. On the other hand, in HDPL, the set of actions is countably infinite for each finite signature with at least one binary relation. This implies that a complete gameboard tree would be infinitely branched.

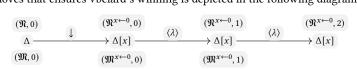
*Example 3.1.* Let  $\Delta$  be a signature with no nominals, one binary relation  $\lambda$ , and one propositional symbol p. Let  $\mathfrak{M}$  and  $\mathfrak{N}$  be the  $\Delta$ -models shown to the left and right, respectively, in the following diagram.<sup>3</sup>



(1) If  $\mathcal{L}$  is DPL, then  $(\mathfrak{M},0)$  and  $(\mathfrak{N},0)$  are  $\mathcal{L}$ -elementarily equivalent. Since there are no nominals and no way to name them in the absence of store,  $\exists$ loise has a winning strategy for all EF games played over any gameboard tree.

<sup>&</sup>lt;sup>3</sup>This example is from the term-rewriting literature: Both models are abstract rewriting systems that are locally confluent but not confluent. In this case, p stands for the normal form property [4]. These concepts play no further role in our study.

(2) If  $\mathcal{L}$  is HPL, then  $(\mathfrak{M}, 0) \not\approx_{tr} (\mathfrak{N}, 0)$  for any complete gameboard tree tr of height greater or equal than 3. The sequence of moves that ensures  $\forall$  belard's winning is depicted in the following diagram.

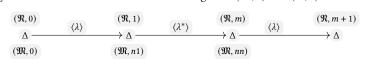


In the third round,  $\exists$  loise's only options are to move back to 0 or to move to b. In both cases the game property is not satisfied.

Example 3.2 ([2, Ex. 5.13]). Let  $\Delta$  be the signature comprising of one binary relation  $\lambda$ . Let  $\mathfrak M$  be the model depicted to the left of the following diagram, which is a countably infinitely branched tree with the root 0. Let  $\mathfrak M$  be the model depicted to the right of the following diagram, which is obtained from  $\mathfrak M$  by adding a new branch of countably infinite length.



- (1) In all fragments of HPL,  $\exists$ loise has a winning strategy for all EF games played over a finite gameboard tree starting with  $(\mathfrak{M}, 0)$  and  $(\mathfrak{N}, 0)$ .
- (2) In any fragment of HDPL closed under Boolean connectives and possibility over structured actions,  $\exists$ loise loses the game played over  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta \xrightarrow{\langle \lambda^* \rangle} \Delta \xrightarrow{\langle \lambda \rangle} \Delta$  starting with  $(\mathfrak{M}, 0)$  and  $(\mathfrak{N}, 0)$ :



First,  $\forall$  belard moves  $(\mathfrak{R}, 0)$  along  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  to obtain  $(\mathfrak{R}, 1)$ . A move from  $\exists$  loise results in  $(\mathfrak{M}, n1)$ , where n is a natural number greater than 0. Then  $\forall$  belard moves  $(\mathfrak{M}, n1)$  along  $\Delta \xrightarrow{\langle \lambda^* \rangle} \Delta$  to obtain  $(\mathfrak{M}, nn)$ .  $\exists$  loise can move  $(\mathfrak{R}, 1)$  along  $\Delta \xrightarrow{\langle \lambda^* \rangle} \Delta$  to get  $(\mathfrak{R}, m)$ , where m is any natural number greater than 1. For the final round,  $\forall$  belard takes  $(\mathfrak{R}, m)$  along  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  to obtain  $(\mathfrak{R}, m+1)$  while  $\exists$  loise cannot match this move.

Example 3.3. Let  $\Delta$  be a signature consisting of one binary relation  $\lambda$ . Let  $\mathfrak{M}$  be the model depicted to the left of the following diagram, comprising a countably infinite number of cycles of increasing length that traverse through 0. Let  $\mathfrak{N}$  be the model depicted to the right of the following diagram, which is obtained from  $\mathfrak{M}$  by adding a countably infinite chain with no end points passing through 0. Then  $(\mathfrak{M}, 0)$  and  $(\mathfrak{N}, 0)$  are elementarily equivalent w.r.t. any fragment  $\mathcal{L}$  of HPL closed under Boolean connectives, but they are not elementarily equivalent in any fragment of HDPL that is closed under Boolean connectives and has possibility over structured actions and store.



∀belard has a winning strategy in three steps:

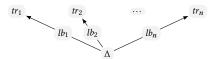
The game starts by naming the current state by both  $\forall$ belard and  $\exists$ loise. Then  $\forall$ belard moves  $(\mathfrak{R}^{x\leftarrow 0}, 0)$  along  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  to obtain  $(\mathfrak{R}^{x\leftarrow 0}, 1)$ .  $\exists$ loise moves along  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  to obtain  $(\mathfrak{R}^{x\leftarrow 0}, n1)$ . For the final round,  $\forall$ belard can return  $(\mathfrak{R}^{x\leftarrow 0}, n1)$  to the state 0 while  $\exists$ loise cannot match this move.

#### 3.3 Game sentences

We propose a notion of game sentence defined over a gameboard tree which describes precisely the EF games played on the gameboard tree given.

Definition 3.4 (Game sentence). The set of game sentences  $\Theta_{tr}$  over a gameboard tree tr, whose root is labelled by a finite signature  $\Delta$ , is defined by structural induction on gameboard trees:

$$tr = \Delta$$
: Let  $\Theta_{\Delta} = \{ \bigwedge_{\rho \in \operatorname{Sen}_b(\Delta)} \rho^{f(\rho)} \mid f : \operatorname{Sen}_b(\Delta) \to \{0,1\} \}$ , where  $\rho^0 = \rho$  and  $\rho^1 = \neg \rho$ .  $tr = \Delta(\xrightarrow{lb_1} tr_1 \dots \xrightarrow{lb_n} tr_n)$ : This case can be depicted as follows:



Let us fix an arbitrary index  $i \in \{1, ..., n\}$ . We will define

- (1) a subsetet  $S_i \subseteq \mathcal{P}(\Theta_{tr_i})$  of the powerset of  $\Theta_{tr_i}$ , and
- (2) a Δ-sentence  $\varphi_{\Gamma}$  for each set of game sentences  $\Gamma \in S_i$ .

Depending on the label  $lb_i$ , there are five cases:

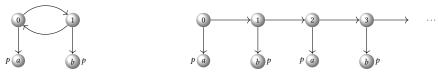
- $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta$ : In this case, we assume that  $\Diamond \in O$ . Then we define:
  - (1)  $S_i := \mathcal{P}(\Theta_{tr_i})$ , the powerset of  $\Theta_{tr_i}$ , and
  - (2)  $\varphi_{\Gamma} := (\bigwedge_{\gamma \in \Gamma} \langle \mathfrak{a} \rangle_{\gamma}) \wedge ([\mathfrak{a}] \vee \Gamma) \text{ for all } \Gamma \in S_i.$
- $\Delta \xrightarrow{@k} \Delta$ : In this case, we assume that  $@ \in O$ . Then we define:
  - (1)  $S_i := \{\{\gamma\} \mid \gamma \in \Theta_{tr_i}\}$ , the set of all singletons with elements from  $\Theta_{tr_i}$ , and
  - (2)  $\varphi_{\{\gamma\}} := @_k \gamma \text{ for all singletons } \{\gamma\} \in S_i$ .
- $\Delta \xrightarrow{\downarrow} \Delta[x]$ : In this case, we assume that  $\downarrow \in O$ . The we define:
  - (1)  $S_i := \{\{\gamma\} \mid \gamma \in \Theta_{tr_i}\}$ , the set of all singletons with elements from  $\Theta_{tr_i}$ , and
  - (2)  $\varphi_{\{\gamma\}} = \downarrow x \cdot \gamma$  for all singletons  $\{\gamma\} \in S_i$ .
- $\Delta \xrightarrow{\exists} \Delta[x]$ : In this case, we assume that  $\exists \in O$ . Then we define:
  - (1)  $S_i := \mathcal{P}(\Theta_{tr_i})$ , the powerset of  $\Theta_{tr_i}$ , and
  - (2)  $\varphi_{\Gamma} := (\bigwedge_{\gamma \in \Gamma} \exists x \cdot \gamma) \land (\forall x \cdot \bigvee \Gamma)$ , for all  $\Gamma \in S_i$ .

 $\Delta \xrightarrow{1} \Delta$ : Then we define:

- (1)  $S_i := \{\{\gamma\} \mid \gamma \in \Theta_{tr_i}\}$ , the set of all singletons with elements from  $\Theta_{tr_i}$ , and
- (2)  $\varphi_{\{\gamma\}} := \gamma$  for all singletons  $\{\gamma\} \in S_i$ .

The set of game sentences over tr is  $\Theta_{tr} = \{ \varphi_{\Gamma_1} \wedge \cdots \wedge \varphi_{\Gamma_n} \mid \Gamma_1 \in S_1, \dots, \Gamma_n \in S_n \}$ .

*Example 3.5.* Assume that  $\mathcal{L}$  is HPL. Recall the signature  $\Delta$ , along with the  $\Delta$ -models  $\mathfrak{M}$  and  $\mathfrak{N}$  introduced in Example 3.1.



Let  $tr_0$  denote the gameboard tree shown in Example 3.1.

$$\Delta \xrightarrow{\hspace*{1cm}} \Delta[x] \xrightarrow{\hspace*{1cm}} \langle \lambda \rangle \xrightarrow{\hspace*{1cm}} \Delta[x] \xrightarrow{\hspace*{1cm}} \langle \lambda \rangle$$

- Let  $tr_{i+1}$  be the immediate subtree of  $tr_i$  for all  $i \in \{0, 1, 2\}$ .
- Note that  $\Theta_{tr_3} = \{x \land p, x \land \neg p, \neg x \land p, \neg x \land \neg p\}.$
- Let  $\Gamma_3 := \{ \neg x \land p, \neg x \land \neg p \}$ .
- Note that  $\Gamma_3 \subseteq \Theta_{tr_3}$  and  $\varphi_{\Gamma_3} = ((\langle \lambda \rangle \neg x \land p) \land \langle \lambda \rangle \neg x \land \neg p) \land ([\lambda] \neg x \land p \lor \neg x \land \neg p) \in \Theta_{tr_2}$ .
- Let  $\Gamma_2 := \{\varphi_{\Gamma_3}\}$  and note that  $\Gamma_2 \subseteq \Theta_{tr_2}$  and  $\varphi_{\Gamma_2} = (\langle \lambda \rangle \varphi_{\Gamma_3}) \wedge ([\lambda] \varphi_{\Gamma_3}) \in \Theta_{tr_1}$ .
- Let  $\Gamma_1 := \{ \varphi_{\Gamma_2} \}$  and note that  $\Gamma_1 \subseteq \Theta_{tr_1}$  and  $\varphi_{\Gamma_1} = \bigcup x \cdot \varphi_{\Gamma_2} \in \Theta_{tr_0}$ .

The diagram below illustrates a winning strategy for  $\forall$ belard in the EF game played on  $tr_0$ .

$$(\mathfrak{R}^{x\leftarrow 0},b) \models \neg x \land p$$

$$(\mathfrak{R}^{x\leftarrow 0},0) \models \varphi_{\Gamma_{2}} \qquad (\mathfrak{R}^{x\leftarrow 0},1) \models \varphi_{\Gamma_{3}} \qquad (\mathfrak{R}^{x\leftarrow 0},2) \models \neg x \land \neg p$$

$$\Delta \longrightarrow \Delta[x] \longrightarrow \Delta[x] \longrightarrow \Delta[x] \qquad (\mathfrak{R}^{x\leftarrow 0},0) \not\models \varphi_{\Gamma_{2}} \qquad (\mathfrak{R}^{x\leftarrow 0},1) \not\models \varphi_{\Gamma_{3}} \qquad (\mathfrak{R}^{x\leftarrow 0},0) \not\models \neg x \land \neg p$$

$$(\mathfrak{R}^{x\leftarrow 0},0) \not\models \varphi_{\Gamma_{2}} \qquad (\mathfrak{R}^{x\leftarrow 0},0) \not\models \neg x \land \neg p$$

$$(\mathfrak{R}^{x\leftarrow 0},b) \models \neg x \land p$$

Since  $(\mathfrak{M}^{x\leftarrow 0},0) \not\models \neg x \land \neg p$  and  $(\mathfrak{M}^{x\leftarrow 0},b) \models \neg x \land p$ , we have  $(\mathfrak{M}^{x\leftarrow 0},1) \not\models \varphi_{\Gamma_3}$ , which implies  $(\mathfrak{M}^{x\leftarrow 0},0) \not\models \varphi_{\Gamma_2}$ ; hence  $(\mathfrak{M},0) \not\models \varphi_{\Gamma_1}$ . Similarly, since  $(\mathfrak{R}^{x\leftarrow 0},b) \models \neg x \land p$  and  $(\mathfrak{R}^{x\leftarrow 0},2) \models \neg x \land \neg p$ , we have  $(\mathfrak{R}^{x\leftarrow 0},1) \models \varphi_{\Gamma_3}$ , which implies  $(\mathfrak{R}^{x\leftarrow 0},0) \models \varphi_{\Gamma_2}$ ; hence  $(\mathfrak{R},0) \models \varphi_{\Gamma_1}$ . We will show that  $\forall$  belard has a winning strategy for the EF game played on  $tr_0$  (as depicted above), because  $(\mathfrak{M},0)$  and  $(\mathfrak{R},0)$  satisfy different game sentences in  $\Theta_{tr_0}$ .

Finite hybrid-dynamic EF games provide an intuitive method for establishing that two pointed models are elementarily equivalent. The following result shows that game sentences characterize precisely finite hybrid-dynamic EF games. In addition, any hybrid-dynamic sentence is semantically equivalent to a game sentence. Therefore, we obtain a characterization theorem for the fragment  $\mathcal{L}$ .

Theorem 3.6 (Fraïssé-Hintikka Theorem). Let  $\Delta$  be a finite signature.

- (1) For all pointed models  $(\mathfrak{M}, w)$  defined over  $\Delta$ , and all gameboard trees tr with root $(tr) = \Delta$ , there exists a unique game sentence  $\varphi \in \Theta_{tr}$  such that  $(\mathfrak{M}, w) \models \varphi$ .
- (2) For all pointed models  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  defined over  $\Delta$  and all gameboard trees tr with root  $(tr) = \Delta$ , the following are equivalent:
  - (a)  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$
  - (b) There exists a unique game sentence  $\varphi \in \Theta_{tr}$  such that  $(\mathfrak{M}, w) \models \varphi$  and  $(\mathfrak{N}, v) \models \varphi$ .

(3) For each sentence  $\phi$  defined over  $\Delta$ , there exists a gameboard tree tr with  $root(tr) = \Delta$  and a set of game sentences  $\Psi_{\phi} \subseteq \Theta_{tr}$  such that  $\phi \leftrightarrow \bigvee \Psi_{\phi}$  is a tautology.

PROOF. For (1), we proceed by induction on gameboard trees tr:

 $tr = \Delta$  Both existence and uniqueness follow directly from the definition of  $\Theta_{\Lambda}$ .

- $tr = \Delta(\frac{lb_1}{\longrightarrow} tr_1 \dots \frac{lb_n}{\longrightarrow} tr_n)$  For the induction step, we show that for all  $i \in \{1, \dots, n\}$  there exists a unique set  $\Gamma^{tr_i}_{(\mathfrak{M}, w)} \subseteq \Theta_{tr_i}$  such that  $(\mathfrak{M}, w) \models \varphi_{\Gamma^{tr_i}_{(\mathfrak{M}, w)}}$ . Let us fix an index  $i \in \{1, \dots, n\}$ . By induction hypothesis, for each pointed model  $(\mathfrak{N}, v)$  defined over the signature  $root(tr_i)$ , there exists a unique game sentence  $\varphi^{tr_i}_{(\mathfrak{N}, v)} \in \Theta_{tr_i}$  such that  $(\mathfrak{N}, v) \models \varphi^{tr_i}_{(\mathfrak{M}, v)}$ . Depending on the label  $lb_i$  we have five cases:
  - $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta \text{ Let } \Gamma^{tr_i}_{(\mathfrak{M},w)} = \{ \varphi^{tr_i}_{(\mathfrak{M},v)} \in \Theta_{tr_i} \mid w \mathfrak{a}^{\mathfrak{M}} v \}, \text{ the set of all game sentences in } \Theta_{tr_i} \text{ satisfied by some pointed model } (\mathfrak{M},v) \text{ such that } w \mathfrak{a}^{\mathfrak{M}} v \text{ holds. Notice that } \Gamma^{tr_i}_{(\mathfrak{M},w)} \in S_i. \text{ Since } \varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}} = (\bigwedge_{\gamma \in \Gamma^{tr_i}_{(\mathfrak{M},w)}} \langle \mathfrak{a} \rangle \gamma) \wedge ([\mathfrak{a}] \bigvee \Gamma^{tr_i}_{(\mathfrak{M},w)}), \text{ we have that } (\mathfrak{M},w) \models \varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}}.$
  - $\Delta \xrightarrow{@k} \Delta \text{ Let } \Gamma^{tr_i}_{(\mathfrak{M},w)} = \{\varphi^{tr_i}_{(\mathfrak{M},k^{\mathfrak{M}})}\}, \text{ where } \varphi^{tr_i}_{(\mathfrak{M},k^{\mathfrak{M}})} \text{ is the unique game sentence in } \Theta_{tr_i} \text{ satisfied by } (\mathfrak{M},k^{\mathfrak{M}})$  By definition,  $\Gamma^{tr_i}_{(\mathfrak{M},w)} \in S_i$ . Since  $\varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}} = @_k \varphi^{tr_i}_{(\mathfrak{M},k^{\mathfrak{M}})}$ , we have that  $(\mathfrak{M},w) \models \varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}}$ .
  - $\Delta \xrightarrow{\downarrow} \Delta[x] \text{ Let } \Gamma^{tr_i}_{(\mathfrak{M},w)} = \{\varphi^{tr_i}_{(\mathfrak{M}^{x\leftarrow w},w)}\}, \text{ where } \varphi^{tr_i}_{(\mathfrak{M}^{x\leftarrow w},w)} \text{ is the unique game sentence in } \Theta_{tr_i} \text{ satisfied by the pointed model } (\mathfrak{M}^{x\leftarrow w},w). \text{ By definition, we have } \Gamma^{tr_i}_{(\mathfrak{M},w)} \in S_i. \text{ Since } \varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}} = \downarrow x \cdot \varphi^{tr_i}_{(\mathfrak{M}^{x\leftarrow w},w)}, \text{ we have that } (\mathfrak{M},w) \models \varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}}.$
  - $\Delta \xrightarrow{\exists} \Delta[x] \text{ Let } \Gamma^{tr_i}_{(\mathfrak{M},w)} = \{ \varphi^{tr_i}_{(\mathfrak{M}^{\kappa\leftarrow v},w)} \in \Theta_{tr_i} \mid v \in |\mathfrak{M}| \}, \text{ the set of all game sentences in } \Theta_{tr_i} \text{ which are satisfied by some } \Delta[x] \text{-expansion } \mathfrak{M}^{x\leftarrow v} \text{ of } \mathfrak{M} \text{ in the state } w. \text{ By definition, we have } \Gamma^{tr_i}_{(\mathfrak{M},w)} \in S_i. \text{ Since } \varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}} = (\bigwedge_{\gamma \in \Gamma^{tr_i}_{(\mathfrak{M},w)}} \exists x \cdot \gamma) \wedge (\forall x \cdot \bigvee \Gamma^{tr_i}_{(\mathfrak{M},w)}), \text{ we obtain } (\mathfrak{M},w) \models \varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}}.$
  - $\Delta \xrightarrow{1} \Delta \text{ Let } \Gamma^{tr_i}_{(\mathfrak{M},w)} = \{\varphi^{tr_i}_{(\mathfrak{M},w)}\} \text{ and } \varphi_{\Gamma^{tr_i}_{(\mathfrak{M},w)}} = \varphi^{tr_i}_{(\mathfrak{M},w)}. \text{ Let } \Gamma^{tr_i}_{(\mathfrak{M},w)} = \{\varphi^{tr_i}_{(\mathfrak{M},w)}\}, \text{ and by definition } \{\varphi^{tr_i}_{(\mathfrak{M},w)}\} \in S_i. \text{ By induction hypothesis, } (\mathfrak{M},w) \models \varphi^{tr_i}_{(\mathfrak{M},w)}.$

Let  $\varphi_{(\mathfrak{M},w)}^{tr} = \varphi_{\Gamma_{(\mathfrak{M},w)}^{tr_1}} \wedge \cdots \wedge \varphi_{\Gamma_{(\mathfrak{M},w)}^{tr_n}}$ . Since  $(\mathfrak{M},w) \models \varphi_{\Gamma_{(\mathfrak{M},w)}^{tr_i}}$  for all  $i \in \{1,\ldots,n\}$ , it follows that  $(\mathfrak{M},w) \models \varphi_{(\mathfrak{M},w)}^{tr}$ , which completes the proof of existence.

We show that  $\varphi_{(\mathfrak{M},w)}^{tr} \in \Theta_{tr}$  is unique. Assume that  $(\mathfrak{M},w) \models \varphi_{\Gamma_1} \wedge \cdots \wedge \varphi_{\Gamma_n}$  where  $\varphi_{\Gamma_1} \wedge \cdots \wedge \varphi_{\Gamma_n} \in \Theta_{tr}$ . It suffices to prove that  $\Gamma_i = \Gamma_{(\mathfrak{M},w)}^{tr_i}$  for all  $i \in \{1,\ldots,n\}$ . We have four cases to consider, one for each type of label.

- $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta \;$  We prove the equality of the sets by double inclusion.
  - $\Gamma_i \subseteq \Gamma_{(\mathfrak{M},w)}^{tr_i}$  Since  $(\mathfrak{M},w) \models \varphi_{\Gamma_i}$ , we have that  $(\mathfrak{M},w) \models \bigwedge_{\gamma \in \Gamma_i} \langle \mathfrak{a} \rangle_{\gamma}$ ; since  $(\mathfrak{M},w) \models \varphi_{\Gamma_{(\mathfrak{M},w)}^{tr_i}}$ , we obtain  $(\mathfrak{M},w) \models [\mathfrak{a}] \vee \Gamma_{(\mathfrak{M},w)}^{tr_i}$ . It follows that  $\Gamma_i \subseteq \Gamma_{(\mathfrak{M},w)}^{tr_i}$ .
  - $(\mathfrak{M},w)\models [\mathfrak{a}]\vee \Gamma_{(\mathfrak{M},w)}^{tr_i}. \text{ It follows that } \Gamma_i\subseteq \Gamma_{(\mathfrak{M},w)}^{tr_i}.$   $\Gamma_{(\mathfrak{M},w)}^{tr_i}\subseteq \Gamma_i \text{ Since } (\mathfrak{M},w)\models \varphi_{\Gamma_{(\mathfrak{M},w)}^{tr_i}}, \text{ we have that } (\mathfrak{M},w)\models \bigwedge_{\gamma\in \Gamma_{(\mathfrak{M},w)}^{tr_i}}\langle \mathfrak{a}\rangle_{\gamma}; \text{ since } (\mathfrak{M},w)\models \varphi_{\Gamma_i}, \text{ we have } (\mathfrak{M},w)\models [\mathfrak{a}]\vee \Gamma_i. \text{ It follows that } \Gamma_{(\mathfrak{M},w)}^{tr_i}\subseteq \Gamma_i.$
- $\Delta \xrightarrow{@_k} \Delta$  Assume that  $\Gamma_i = \{\gamma\}$ , where  $\gamma \in \Theta_{tr_i}$ . Recall that  $\varphi_{\Gamma_i} = @_k \gamma$ . We have  $(\mathfrak{M}, w) \models \varphi_{\Gamma_i}$  iff  $(\mathfrak{M}, w) \models @_k \gamma$  iff  $(\mathfrak{M}, k^{\mathfrak{M}}) \models \gamma$ . It follows that  $\gamma$  is  $\varphi_{(\mathfrak{M}, k^{\mathfrak{M}})}^{tr_i}$ , the unique game sentence in  $\Theta_{tr_i}$  satisfied by  $(\mathfrak{M}, k^{\mathfrak{M}})$ . By definition,  $\Gamma_i = \Gamma_{(\mathfrak{M}, k^{\mathfrak{M}})}^{tr_i}$ .

 $\Delta \xrightarrow{\downarrow} \Delta[x]$  This case is similar to the one corresponding to  $\Delta \xrightarrow{@k} \Delta$ .  $\Delta \xrightarrow{\exists} \Delta[x]$  This case is similar to the one corresponding to  $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta$ .  $\Delta \xrightarrow{1} \Delta$  This case is a simplification of the case corresponding to  $\Delta \xrightarrow{@k} \Delta$ .

Also for (2), we proceed by induction on gameboard trees tr:

 $tr = \Delta$  In this case, the equivalence of statements (2a) and (2b) follows directly from the definition of  $\Theta_{\Delta}$ .  $tr = \Delta(\xrightarrow{lb_1} tr_1 \dots \xrightarrow{lb_n} tr_n)$  For the forward implication, assume that  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ . We show that  $\varphi^{tr}_{(\mathfrak{M}, w)} = tr$  $\varphi^{tr}_{(\mathfrak{N},v)}$ , which is equivalent to  $\Gamma^{tr_i}_{(\mathfrak{M},w)} = \Gamma^{tr_i}_{(\mathfrak{N},v)}$  for all  $i \in \{1,\ldots,n\}$ . Let us fix an index  $i \in \{1,\ldots,n\}$ . Depending on the label  $lb_i$ , we have five cases:

 $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta$  We show the equality by double inclusion.

 $\Gamma_{(\mathfrak{M},w)}^{tr_i}\subseteq\Gamma_{(\mathfrak{N},v)}^{tr_i} \text{ Let } \gamma\in\Gamma_{(\mathfrak{M},w)}^{tr_i}. \text{ By the definition of } \Gamma_{(\mathfrak{M},w)}^{tr_i}, \text{ there exists a state } w_i\in\mathfrak{a}^{\mathfrak{M}}(w) \text{ such that } w\in\mathfrak{A}^{\mathfrak{M}}(w)$  $(\mathfrak{M}, w_i) \models \gamma$ . Since  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ , there exists a state  $v_i \in \mathfrak{a}^{\mathfrak{N}}(v)$  such that  $(\mathfrak{M}, w_i) \approx_{tr_i} (\mathfrak{N}, v_i)$ . By induction hypothesis,  $(\mathfrak{M}, w_i) \models \gamma$  and  $(\mathfrak{N}, v_i) \models \gamma$ . By the definition of  $\Gamma_{(\mathfrak{N}, v)}^{tr_i}$  we obtain 
$$\begin{split} \gamma \in \Gamma_{(\mathfrak{N},v)}^{tr_i}. \\ \Gamma_{(\mathfrak{N},v)}^{tr_i} \subseteq \Gamma_{(\mathfrak{M},w)}^{tr_i} &\text{ This case is symmetric to the one above.} \end{split}$$

 $\Delta \xrightarrow{@k} \Delta$  Since  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ , we have  $(\mathfrak{M}, k^{\mathfrak{M}}) \approx_{tr_i} (\mathfrak{N}, k^{\mathfrak{N}})$ . By induction hypothesis, we have  $\varphi_{(\mathfrak{M},k^{\mathfrak{M}})}^{tr_{i}}=\varphi_{(\mathfrak{M},k^{\mathfrak{M}})}^{tr_{i}}. \text{ It follows that } \Gamma_{(\mathfrak{M},w)}^{tr_{i}}=\{\varphi_{(\mathfrak{M},k^{\mathfrak{M}})}^{tr_{i}}\}=\{\varphi_{(\mathfrak{M},k^{\mathfrak{M}})}^{tr_{i}}\}=\Gamma_{(\mathfrak{M},v)}^{tr_{i}}.$ 

 $\Delta \xrightarrow{\downarrow} \Delta[x]$  Since  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ , we have  $(\mathfrak{M}^{x \leftarrow w}, w) \approx_{tr} (\mathfrak{N}^{x \leftarrow v}, v)$ . By induction hypothesis, we have  $\varphi_{(\mathfrak{M}^{x\leftarrow w},w)}^{tr_{i}} = \varphi_{(\mathfrak{M}^{x\leftarrow v},n)}^{tr_{i}}. \text{ It follows that } \Gamma_{(\mathfrak{M}^{w},w)}^{tr_{i}} = \{\varphi_{(\mathfrak{M}^{x\leftarrow w},w)}^{tr_{i}}\} = \{\varphi_{(\mathfrak{M}^{x\leftarrow v},n)}^{tr_{i}}\} = \Gamma_{(\mathfrak{M}^{x},n)}^{tr_{i}}.$ 

 $\Delta \xrightarrow{\exists} \Delta[x]$  We show the equality by double inclusion.

 $\Gamma^{tr_i}_{(\mathfrak{M},w)} \subseteq \Gamma^{tr_i}_{(\mathfrak{N},v)}$  Let  $\gamma \in \Gamma^{tr_i}_{(\mathfrak{M},w)}$ . By the definition of  $\Gamma^{tr_i}_{(\mathfrak{M},w)}$  there exists a  $w_i \in |\mathfrak{M}|$  such that  $(\mathfrak{M}^{x \leftarrow w_i}, w) \models \gamma$ . Since  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ , there exists a  $v_i \in |\mathfrak{N}|$  such that  $(\mathfrak{M}^{x \leftarrow w_i}, w) \approx_{tr_i}$  $(\mathfrak{N}^{x\leftarrow v_i}, v)$ . By the induction hypothesis,  $(\mathfrak{M}^{x\leftarrow w_i}, w) \models \gamma$  and  $(\mathfrak{N}^{x\leftarrow v_i}, v) \models \gamma$ . By the definition of  $\Gamma_{(\mathfrak{N},v)}^{tr_i}$ , we obtain  $\gamma \in \Gamma_{(\mathfrak{N},v)}^{tr_i}$ 

 $\Gamma^{tr_i}_{(\mathfrak{N},v)}\subseteq \Gamma^{tr_i}_{(\mathfrak{M},w)}$  This case is symmetric to the one above.

 $\Delta \xrightarrow{1} \Delta$  Since  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ , we have  $(\mathfrak{M}, w) \approx_{tr_i} (\mathfrak{N}, v)$ . By induction hypothesis, we have  $\varphi_{(\mathfrak{M}, w)}^{tr_i} = \varphi_{(\mathfrak{M}, w)}^{tr_i} = \varphi_{(\mathfrak{M}, w)}^{tr_i}$  $\varphi_{(\mathfrak{M},v)}^{tr_i}$ . It follows that  $\Gamma_{(\mathfrak{M},w)}^{tr_i} = \{\varphi_{(\mathfrak{M},w)}^{tr_i}\} = \{\varphi_{(\mathfrak{M},v)}^{tr_i}\} = \Gamma_{(\mathfrak{N},v)}^{tr_i}$ .

For the backward implication, assume a unique  $\varphi_{\Gamma_1} \wedge \cdots \wedge \varphi_{\Gamma_n} \in \Theta_{tr}$  such that  $(\mathfrak{M}, w) \models \varphi_{\Gamma_1} \wedge \cdots \wedge \varphi_{\Gamma_n}$  and  $(\mathfrak{N}, v) \models \varphi_{\Gamma_1} \land \cdots \land \varphi_{\Gamma_n}$ . We show that  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ . Assume that  $\forall$  belard moves along an edge labeled  $lb_i$  of tr. Depending on the label  $lb_i$ , we have five cases:

- $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta$  Assume that  $\forall$  belard has chosen  $w_i \in \mathfrak{a}^{\mathfrak{M}}(w)$ . Since  $(\mathfrak{M}, w) \models \varphi_{\Gamma_i}$ , we have  $(\mathfrak{M}, w) \models [\mathfrak{a}] \vee \Gamma_i$ . By semantics,  $(\mathfrak{M}, w_i) \models \gamma_i$  for some  $\gamma_i \in \Gamma_i$ . Since  $(\mathfrak{N}, v) \models \varphi_{\Gamma_i}$ , we have  $(\mathfrak{N}, v) \models \bigwedge_{\psi \in \Gamma_i} \langle \mathfrak{a} \rangle \psi$ . Since  $\gamma_i \in \Gamma_i$ , we obtain  $(\mathfrak{R}, v) \models \langle \mathfrak{a} \rangle \gamma_i$ . By semantics, there exists  $v_i \in \mathfrak{a}^{\mathfrak{R}}(v)$  such that  $(\mathfrak{R}, v_i) \models \gamma_i$ . Since  $(\mathfrak{M}, w_i) \models \gamma_i$ and  $(\mathfrak{N}, v_i) \models \gamma_i$ , by induction hypothesis,  $(\mathfrak{M}, w_i) \approx_{tr_i} (\mathfrak{N}, v_i)$ .
- $\Delta \xrightarrow{@_k} \Delta$  In this case,  $\Gamma_i = \{\gamma_i\}$  for some  $\gamma_i \in \Theta_{tr_i}$  and  $\varphi_{\Gamma_i} = @_k \gamma_i$ . We have that  $(\mathfrak{M}, w) \models @_k \gamma_i$ , which means  $(\mathfrak{M}, k^{\mathfrak{M}}) \models \gamma_i$ . Similarly,  $(\mathfrak{N}, v) \models @_k \gamma_i$ , which means  $(\mathfrak{N}, k^{\mathfrak{N}}) \models \gamma_i$ . Since  $(\mathfrak{M}, k^{\mathfrak{M}}) \models \gamma_i$  and  $(\mathfrak{N}, k^{\mathfrak{N}}) \models \gamma_i$ , by induction hypothesis,  $(\mathfrak{M}, k^{\mathfrak{M}}) \approx_{tr_i} (\mathfrak{N}, k^{\mathfrak{N}})$ .

- $\Delta \xrightarrow{\downarrow} \Delta[x]$  In this case,  $\Gamma_i = \{\gamma_i\}$  for some  $\gamma_i \in \Theta_{tr_i}$  and  $\varphi_{\Gamma_i} = \downarrow x \cdot \gamma_i$ . We have that  $(\mathfrak{M}, w) \models \downarrow x \cdot \gamma_i$ , which means  $(\mathfrak{M}^{x \leftarrow w}, w) \models \gamma_i$ . Similarly,  $(\mathfrak{N}, v) \models \downarrow x \cdot \gamma_i$ , which means  $(\mathfrak{N}^{x \leftarrow v}, v) \models \gamma_i$ . Since  $(\mathfrak{M}^{x \leftarrow w}, w) \models \gamma_i$  and  $(\mathfrak{N}^{x \leftarrow v}, v) \models \gamma_i$ , by induction hypothesis,  $(\mathfrak{M}^{x \leftarrow w}, w) \approx_{tr_i} (\mathfrak{N}^{x \leftarrow v}, v)$ .
- $\Delta \stackrel{\exists}{\to} \Delta[x]$  Assume that  $\forall$  belard has chosen  $w_i \in |\mathfrak{M}|$ . Since  $(\mathfrak{M}, w) \models \varphi_{\Gamma_i}$ , we have  $(\mathfrak{M}, w) \models \forall x \cdot \bigvee \Gamma_i$ . By semantics,  $(\mathfrak{M}^{x \leftarrow w_i}, w) \models \gamma_i$  for some  $\gamma_i \in \Gamma_i$ . Since  $(\mathfrak{N}, v) \models \varphi_{\Gamma_i}$ , we have  $(\mathfrak{N}, v) \models \bigwedge_{\psi \in \Gamma_i} \exists x \cdot \psi$ . Since  $\gamma_i \in \Gamma_i$ , we obtain  $(\mathfrak{N}, v) \models \exists x \cdot \gamma_i$ . By semantics,  $(\mathfrak{N}^{x \leftarrow v_i}, v) \models \gamma_i$  for some  $v_i \in |\mathfrak{N}|$ . Since  $(\mathfrak{M}^{x \leftarrow w_i}, w) \models \gamma_i$  and  $(\mathfrak{N}^{x \leftarrow v_i}, v) \models \gamma_i$ , by induction hypothesis,  $(\mathfrak{M}^{x \leftarrow w_i}, w) \approx_{tr_i} (\mathfrak{N}^{x \leftarrow v_i}, v)$ .
- $\Delta \xrightarrow{1} \Delta$  In this case,  $\Gamma_i = \{\gamma_i\}$  for some  $\gamma_i \in \Theta_{tr_i}$  and  $\varphi_{\Gamma_i} = \gamma_i$ . We have that  $(\mathfrak{M}, w) \models \gamma_i$ . Similarly,  $(\mathfrak{N}, v) \models \gamma_i$ . Since  $(\mathfrak{M}, w) \models \gamma_i$  and  $(\mathfrak{N}, v) \models \gamma_i$ , by induction hypothesis,  $(\mathfrak{M}, w) \approx_{tr_i} (\mathfrak{N}, v)$ .

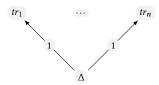
It follows that  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ .

For (3), we proceed by induction on the structure of  $\phi$ :

- $\phi \in \operatorname{Sen}_b(\Delta)$  Let  $\Psi_{\phi}$  be the set of game sentences in  $\Theta_{\Delta}$  in which  $\phi$  occurs positively. It is straightforward to see that  $\bigvee \Psi_{\phi} \leftrightarrow \phi$  is a tautology.
- $\neg \phi$  By induction hypothesis,  $\phi \leftrightarrow \bigvee \Psi_{\phi}$  for some gameboard tree tr and some  $\Psi_{\phi} \subseteq \Theta_{tr}$ . Define the following set of game sentences over  $tr: \Psi_{\neg \phi} = \Theta_{tr} \setminus \Psi_{\phi}$ . We show that  $\neg \phi \leftrightarrow \bigvee \Psi_{\neg \phi}$  is a tautology:
  - $(\mathfrak{M}, w) \models \neg \phi \iff \text{(by semantics)}$
  - $(\mathfrak{M}, w) \not\models \phi \iff (\text{since } \phi \leftrightarrow \bigvee \Psi_{\phi} \text{ is a tautology})$
  - $(\mathfrak{M}, w) \not\models \bigvee \Psi_{\phi} \iff (\text{by (1), which asserts that } (\mathfrak{M}, w) \models \gamma \text{ for some unique } \gamma \in \Theta_{tr})$
  - $(\mathfrak{M}, w) \models \gamma \text{ for some } \gamma \in \Theta_{tr} \setminus \Psi_{\phi} \iff (\text{since } \Psi_{\neg \phi} = \Theta_{tr} \setminus \Psi_{\phi})$
  - $(\mathfrak{M}, w) \models \bigvee \Psi_{\neg \phi}.$

Hence,  $(\mathfrak{M}, w) \models \neg \phi \leftrightarrow \bigvee \Psi_{\neg \phi}$ .

 $\wedge \Phi$  Assume that  $\Phi = \{\phi_1, \dots, \phi_n\}$ . By induction hypothesis, for all indexes  $i \in \{1, \dots, n\}$ ,  $\phi_i \leftrightarrow \bigvee \Psi_{\phi_i}$  is a tautology for some gameboard tree  $tr_i$  and some set of game sentences  $\Psi_{\phi_i} \subseteq \Theta_{tr_i}$ . We construct a new gameboard tree  $tr = \Delta(\xrightarrow{1} tr_1, \dots, \xrightarrow{1} tr_n)$ .



Define the following set of game sentences over *tr*:

$$\Psi_{\wedge \Phi} = \{ \psi_1 \wedge \cdots \wedge \psi_n \mid \psi_1 \in \Psi_{\phi_1} \dots \psi_n \in \Psi_{\phi_n} \}$$

For all pointed models  $(\mathfrak{M}, w)$ , we have  $(\mathfrak{M}, w) \models \bigwedge \Phi$  iff  $(\mathfrak{M}, w) \models \bigwedge_{i=1}^{n} (\bigvee \Psi_{\phi_i})$  iff  $(\mathfrak{M}, w) \models \bigvee \{\psi_1 \wedge \cdots \wedge \psi_n \mid \psi_1 \in \Psi_{\phi_1}, \dots, \psi_n \in \Psi_{\phi_n}\}$  iff  $(\mathfrak{M}, w) \models \bigvee \Psi_{\bigwedge \Phi}$ . Hence,  $(\mathfrak{M}, w) \models \bigwedge \Phi \leftrightarrow \bigvee \Psi_{\bigwedge \Phi}$ .

 $\langle \mathfrak{a} \rangle \phi$  By induction hypothesis,  $\phi \leftrightarrow \bigvee \Psi_{\phi}$  for some gameboard tree  $tr_0$  with  $root(tr_0) = \Delta$  and some set of game sentences  $\Psi_{\phi} \subseteq \Theta_{tr_0}$ . We construct a new gameboard tree  $tr = \Delta \xrightarrow{\langle \mathfrak{a} \rangle} tr_0$ . We have that  $(\mathfrak{M}, w) \models \langle \mathfrak{a} \rangle \phi$  iff (since  $\phi \leftrightarrow \bigvee \Psi_{\phi}$  is a tautology)  $(\mathfrak{M}, w) \models \langle \mathfrak{a} \rangle \bigvee \Psi_{\phi}$  iff  $(\mathfrak{M}, v) \models \bigvee \Psi_{\phi}$  for some  $v \in \mathfrak{a}^{\mathfrak{M}}(w)$  iff (since  $\Gamma^{tr_0}_{(\mathfrak{M}, w)} = \{\varphi^{tr_0}_{(\mathfrak{M}, w')} \in \Theta_{tr_0} \mid w \mathfrak{a}^{\mathfrak{M}} w'\}\}$   $\Gamma^{tr_0}_{(\mathfrak{M}, w)} \cap \Psi_{\phi} \neq \emptyset$ . Define the following set of game sentences over tr:

- $\Psi_{\langle \mathfrak{a} \rangle \phi} = \{ \varphi_{\Gamma} \mid \Gamma \subseteq \Theta_{tr_0} \text{ such that } \Gamma \cap \Psi_{\phi} \neq \emptyset \}. \text{ Then } (\mathfrak{M}, w) \models \langle \mathfrak{a} \rangle \phi \text{ iff } \Gamma_{(\mathfrak{M}, w)}^{tr_0} \cap \Psi_{\phi} \neq \emptyset \text{ iff (by the definition of } \Psi_{\langle \mathfrak{a} \rangle \phi}) (\mathfrak{M}, w) \models \bigvee \Psi_{\langle \mathfrak{a} \rangle \phi}.$
- $@_k \phi$  By induction hypothesis,  $\phi \leftrightarrow \bigvee \Psi_{\phi}$  is a tautology for some gameboard tree  $tr_0$  and some set of game sentences  $\Psi_{\phi} \subseteq \Theta_{tr_0}$ . Define a new tree  $tr = \Delta \xrightarrow{@_k} tr_0$  and a the following set of game sentences over tr:  $\Psi_{(@_k \phi)} = \{@_k \psi \mid \psi \in \Psi_{\phi}\}$ . Since  $\phi \leftrightarrow \bigvee \Psi_{\phi}$  is a tautology,  $@_k \phi \leftrightarrow \bigvee_{\psi \in \Psi_{\phi}} @_k \psi$  is a tautology, too.
- $\downarrow x \cdot \phi$  By induction hypothesis,  $\phi \leftrightarrow \bigvee \Psi_{\phi}$  is a tautology for some gameboard tree  $tr_x$  with  $root(tr_x) = \Delta[x]$  and some set of game sentences  $\Psi_{\phi} \subseteq \Theta_{tr_x}$ . Define a new tree  $tr = \Delta \xrightarrow{\downarrow} tr_x$  and the following set of game sentences over  $tr: \Psi_{(\downarrow x \cdot \phi)} = \{ \downarrow x \cdot \psi \mid \psi \in \Psi_{\phi} \}$ . Since  $\phi \leftrightarrow \bigvee \Psi_{\phi}$  is a tautology,  $\downarrow x \cdot \phi \leftrightarrow \bigvee \{ \downarrow x \cdot \psi \mid \psi \in \Psi_{\phi} \}$  is a tautology, too.
- $\exists x \cdot \phi \text{ By induction hypothesis, } \phi \leftrightarrow \bigvee \Psi_{\phi} \text{ for some gameboard tree } tr_{X} \text{ with } root(tr_{X}) = \Delta[x] \text{ and some set of game sentence } \Psi_{\phi} \subseteq \Theta_{tr_{X}}. \text{ We construct a new gameboard tree } tr = \Delta \xrightarrow{\exists} tr_{X}. \text{ The following are equivalent: } (\mathfrak{M}, w) \models \exists x \cdot \phi \text{ iff (since } \phi \leftrightarrow \bigvee \Psi_{\phi} \text{ is a tautology) } (\mathfrak{M}, w) \models \exists x \cdot \bigvee \Psi_{\phi} \text{ iff } (\mathfrak{M}^{x \leftarrow v}, v) \models \bigvee \Psi_{\phi} \text{ for some } v \in |\mathfrak{M}| \text{ iff (since } \Gamma^{tr_{X}}_{(\mathfrak{M}, w)} = \{\varphi^{tr_{X}}_{(\mathfrak{M}^{x \leftarrow v'}, w)} \in \Theta_{tr_{X}} \mid w' \in |\mathfrak{M}| \}) \Gamma^{tr_{X}}_{(\mathfrak{M}, w)} \cap \Psi_{\phi} \neq \emptyset. \text{ Define the following set of game sentences over } tr: \Psi_{\exists x \cdot \phi} = \{\varphi_{\Gamma} \mid \Gamma \subseteq \Theta_{tr_{X}} \text{ such that } \Gamma \cap \Psi_{\phi} \neq \emptyset \}. \text{ Then } (\mathfrak{M}, w) \models \exists x \cdot \phi \text{ iff } \Gamma^{tr_{X}}_{(\mathfrak{M}, w)} \cap \Psi_{\phi} \neq \emptyset \text{ iff (by the definition of } \Psi_{\exists x \cdot \phi}) (\mathfrak{M}, w) \models \bigvee \Psi_{\exists x \cdot \phi}. \square$

Theorem 3.6 is applicable to any fragment of HDPL, including classical dynamic propositional logic for which such a result does not exist. The proof of Theorem 3.6 is fundamentally different from the classical case of single-sorted first-order logic, since it relies on the construction of gameboard trees which play the role of quantifier rank. If the fragment  $\mathcal{L}$  is closed under possibility, then there is no normal form of sentences in which first-order quantifiers are moved to the front and then store, retrieve and the Boolean connectives are placed after. For this reason, the proof of the third statement requires idle moves, which serve to construct complex gameboard trees from simpler ones and to define game sentences that are semantically equivalent to conjunctions. Notice that the above results can be straightforwardly extended to logical frameworks which allow infinitary conjunctions by constructing infinitely branched gameboard trees

The following result is a corollary of Theorem 3.6 and it says that two pointed models are elementarily equivalent if  $\exists$ loise has a winning strategy for the EF games played over all gameboard trees.

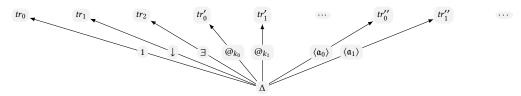
COROLLARY 3.7. Let  $\mathfrak M$  and  $\mathfrak N$  be two Kripke structures defined over a finite signature  $\Delta$ . The following are equivalent:

- (1)  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  are  $\mathcal{L}$ -elementarily equivalent, in symbols  $(\mathfrak{M}, w) \equiv (\mathfrak{N}, v)$ .
- (2)  $\exists$  loise has a winning strategy for the EF game starting with  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$ , that is,  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$  for all gameboard trees tr.

# 4 COUNTABLE EHRENFEUCHT-FRAÏSSÉ GAMES

The construction of gameboard trees of countably infinite height is straightforward. Unlike finitary Ehrenfeucht-Fraïssé games, for countably infinite Ehrenfeucht-Fraïssé games, called  $\omega$ -EF games for short, we consider only *complete gameboard trees of height*  $\omega$ , that is, gameboard trees tr satisfying the following property:

(†) tr is of the following form



where

- $F = \{k_i \mid i < \alpha\}$  is an enumeration of all  $\Delta$ -nominals and  $\alpha$  is the cardinal of Sen( $\Delta$ ),
- $\mathcal{A}(\Delta) = \{\mathfrak{a}_i \mid i < \alpha\}$  is an enumeration of all actions defined over  $\Delta$ , and
- all  $tr_0, tr_1, tr_2, tr_i'$  and  $tr_i''$  from the diagram above satisfy property  $(\dagger)$ .

Similarly to the finitary case,  $\exists$  loise loses the game if the game property is not satisfied by the current pair of pointed models;  $\exists$  loise wins the game if she can match any move made by  $\forall$  belard such that the game property is satisfied. We write  $(\mathfrak{M}, w) \approx_{\omega} (\mathfrak{N}, v)$  if  $\exists$  loise has a winning strategy for all EF games played over the complete gameboard tree of height  $\omega$ .

# 4.1 Bisimulations and countable EF games

We adapt the notion of bisimulation proposed in [3] to our hybrid-dynamic setting. Then we show that the equivalence determined by countable EF games is an  $\omega$ -bisimilarity.

Definition 4.1 ( $\omega$ -bisimulation). Let  $\mathfrak{M}$  and  $\mathfrak{N}$  be Kripke structures. A relation  $B_{\ell} \subseteq (|\mathfrak{M}|^{\ell} \times |\mathfrak{M}|) \times (|\mathfrak{N}|^{\ell} \times |\mathfrak{N}|)$  is an  $\ell$ -bisimulation from  $\mathfrak{M}$  to  $\mathfrak{N}$  if for all  $(\overline{w}, w)$   $B_{\ell}$   $(\overline{v}, v)$  the following hold:

**(prop)**  $p \in M(w)$  iff  $p \in N(v)$  for all propositional symbols  $p \in Prop$ ;

**(nom)**  $w = k^{\mathfrak{M}}$  iff  $v = k^{\mathfrak{N}}$  for all nominals  $k \in F$ ;

(wvar)  $\overline{w}(j) = w \text{ iff } \overline{v}(j) = v \text{ for all } 1 \leq j \leq \ell; ^4$ 

(forth) if  $\diamond \in O$  then for all actions  $\mathfrak{a} \in \mathcal{A}(\Delta)$  and all states  $w' \in \mathfrak{a}^{\mathfrak{M}}(w)$  there exists  $v' \in \mathfrak{a}^{\mathfrak{N}}(v)$  such that  $(\overline{w}, w')$   $B_{\ell}(\overline{v}, v')$ ;

**(back)** if  $\diamond \in O$  then for all actions  $\mathfrak{a} \in \mathcal{A}(\Delta)$  and all states  $v' \in \mathfrak{a}^{\mathfrak{N}}(v)$  there exists  $w' \in \mathfrak{a}^{\mathfrak{M}}(w)$  such that  $(\overline{w}, w')$   $B_{\ell}(\overline{v}, v')$ ;

(atv) if  $@ \in O$  then  $(\overline{w}, \overline{w}(j))$   $B_{\ell}(\overline{v}, \overline{v}(j))$  for all  $1 \le j \le \ell$ ; <sup>5</sup>

**(atn)** if  $@ \in O$  then  $(\overline{w}, k^{\mathfrak{M}})$   $B_{\ell}$   $(\overline{v}, k^{\mathfrak{N}})$  for all nominals  $k \in F$ :

An  $\omega$ -bisimulation from  $\mathfrak{M}$  to  $\mathfrak{N}$  is a family of  $\ell$ -bisimulations  $B = (B_{\ell})_{\ell \in \omega}$  from  $\mathfrak{M}$  to  $\mathfrak{N}$  such that for all natural numbers  $\ell \in \omega$  and all tuples  $(\overline{w}, w) \in |\mathfrak{M}|^{\ell} \times |\mathfrak{M}|$  and  $(\overline{v}, v) \in |\mathfrak{N}|^{\ell} \times |\mathfrak{N}|$  the following conditions are satisfied:

(st) if  $\downarrow \in O$  and  $(\overline{w}, w)$   $B_{\ell}$   $(\overline{v}, v)$  then  $(\overline{w}, w)$   $B_{\ell+1}$   $(\overline{v}, v)$ ,

where the juxtaposition stands for the concatenation of sequences; and

**(ex)** if  $\exists \in O$  and  $(\overline{w}, w)$   $B_{\ell}$   $(\overline{v}, v)$  then:

**(ex-f)** for all  $w' \in |\mathfrak{M}|$  there is  $v' \in |\mathfrak{M}|$  such that  $(\overline{w} \ w', w) \ B_{\ell+1} \ (\overline{v} \ v', v)$ ,

**(ex-b)** for all  $v' \in |\mathfrak{N}|$  there is  $w' \in |\mathfrak{M}|$  such that  $(\overline{w} \ w', w) \ B_{\ell+1} \ (\overline{v} \ v', v)$ .

Two pointed models  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  are  $\omega$ -bisimilar if there exists an  $\omega$ -bisimulation B from  $\mathfrak{M}$  to  $\mathfrak{N}$  such that w  $B_0$  v. In this case, we write  $(\mathfrak{M}, w) \equiv_B^{\mathcal{L}} (\mathfrak{N}, v)$ . Note that an  $\omega$ -bisimulation is a relation between  $|\mathfrak{M}|^*$  and  $|\mathfrak{N}|^*$ .

 $<sup>{}^4\</sup>overline{w}(j)$  and  $\overline{v}(j)$  denote the elements at position j in the sequences  $\overline{w}$  and  $\overline{v}$ , respectively.

<sup>&</sup>lt;sup>5</sup>The elements of  $\overline{w}$  and  $\overline{v}$  can be regarded as named states. Then, in accordance with (atv), the current states w and v are updated to the named states  $\overline{w}(j)$  and  $\overline{v}(j)$ , respectively.

When there is no danger of confusion, we drop the superscript  $\mathcal{L}$  from the notation  $\equiv_B^{\mathcal{L}}$ . Definition 4.1 is obtained from the definition of  $\omega$ -bisimulation from [3, Sect. 3.3] by removing the condition (bind), which already is covered by rule (st).

LEMMA 4.2. Assume an  $\omega$ -bisimulation B between  $(\mathfrak{M}, \mu)$  and  $(\mathfrak{N}, v)$  such that  $(\mu, \mu')$   $B_1$  (v, v') for some tuples  $(\mu, \mu') \in |\mathfrak{M}| \times |\mathfrak{M}|$  and  $(v, v') \in |\mathfrak{N}| \times |\mathfrak{N}|$ . Let be  $\chi : \Delta \to \Delta[x]$  be a signature extension with a variable x. Then  $B^x = (B_\ell^x)_{\ell \in \omega}$  defined by

$$(\overline{w}, w) \ B_{\ell}^{x} \ (\overline{v}, v) \ iff (\mu \overline{w}, w) \ B_{\ell+1} \ (\nu \overline{v}, v),$$

$$for \ all \ \ell \in \omega, \ all \ (\overline{w}, w) \in |\mathfrak{M}|^{\ell} \times |\mathfrak{M}| \ and \ all \ (\overline{v}, v) \in |\mathfrak{M}|^{\ell} \times |\mathfrak{M}|,$$

is a bisimulation between  $(\mathfrak{M}^{x\leftarrow\mu}, \mu')$  and  $(\mathfrak{N}^{x\leftarrow\nu}, \nu')$ .

PROOF. First, notice that  $\mu'$   $B_0^x$  v'. Secondly, we show that all conditions from Definition 4.1 are satisfied. Assume that  $(\overline{w}, w)$   $B_{\ell}^x$   $(\overline{v}, v)$ , which is equivalent to  $(\mu \overline{w}, w)$   $B_{\ell+1}$   $(\nu \overline{v}, v)$ .

```
(prop) For all p \in Prop we have:
     p \in M^{x \leftarrow \mu}(w) \iff (\text{since } M^{x \leftarrow \mu}(w) = M(w))
     p \in M(w) \iff (\text{since } (\mu \, \overline{w}, w) \, B_{\ell+1} (\nu \, \overline{v}, v))
     p \in N(v) \iff (\text{since } N^{x \leftarrow v}(v) = N(v))
     p \in N^{x \leftarrow v}(v).
(nom) For all k \in F we have:
     w = k^{(\mathfrak{M}^{x \leftarrow \mu})} \iff \text{(since } k^{(\mathfrak{M}^{x \leftarrow \mu})} = k^{\mathfrak{M}} \text{)}
     w = k^{\mathfrak{M}} \iff (\text{since } (\mu \overline{w}, w) \ B_{\ell+1} \ (\nu \overline{v}, v))
     v = k^{\mathfrak{N}} \iff (\text{since } k^{\mathfrak{N}} = k^{(\mathfrak{N}^{x \leftarrow v})})
     v = k^{(\mathfrak{N}^{x \leftarrow v})}.
     In addition we have:
     w = x^{(\mathfrak{M}^{x \leftarrow \mu})} \iff (\text{since } x^{(\mathfrak{M}^{x \leftarrow \mu})} = \mu)
     w = \mu \iff \text{(by (wvar), since } (\mu \overline{w}, w) \ B_{\ell+1} \ (\nu \overline{v}, v))
     v = v \iff (\text{since } v = x^{(\mathfrak{N}^{x \leftarrow v})})
     v = x^{(\Re^{x \leftarrow \nu})}.
(wvar) For all 1 \le j \le \ell we have:
     w = \overline{w}(j) \iff (by (wvar), since (\mu \overline{w}, w) B_{\ell+1} (\nu \overline{v}, v))
     v = \overline{v}(j).
(forth) Let \mathfrak{a} \in A be an action and let w' \in \mathfrak{a}^{\mathfrak{M}}(w) be a state.
     Since (\mu \overline{w}, w) B_{\ell+1} (\nu \overline{v}, v), by (forth), (\mu \overline{w}, w') B_{\ell+1} (\nu \overline{v}, v') for some v' \in \mathfrak{a}^{\mathfrak{N}}(v).
     By the definition of B^x, we get (\overline{w}, w') B^x_{\ell} (\overline{v}, v').
(back) Similar to (forth).
(st) By (st) for B, we have (\mu \overline{w} w, w) B_{\ell+2} (\nu \overline{v} v, v).
     By the definition of B^x, we get (\overline{w} w, w) B_{\ell+1}^x (\overline{v} v, v).
(ex-f) Let w' \in |\mathfrak{M}| be any state from \mathfrak{M}.
     By (ex-f) property of B, (\mu \overline{w} w', w) B_{\ell+2} (\nu \overline{v} v', v) for some v' \in |\mathfrak{N}|.
     By the definition of B^x, we get (\overline{w} w', w) B_{\ell+1}^x (\overline{v} v', v).
(ex-b) Similar to (ex-f).
```

Notice that if  $\downarrow \in O$  or  $\exists \in O$ , then  $B^x$  defined in the lemma above is not empty.

Theorem 4.3 (Bisimulations vs. Ehrenfeucht-Fraissé games). Let  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  be two pointed models defined over a signature  $\Delta$ . Then:

$$(\mathfrak{M}, w) \equiv_B (\mathfrak{N}, v)$$
 iff  $(\mathfrak{M}, w) \approx_{\omega} (\mathfrak{N}, v)$ .

PROOF. For the forward implication, assume an  $\omega$ -bisimulation B between  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$ . By (prop) and (nom),  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  satisfy the same atomic sentences. We show that each move made by  $\forall$ belard can be matched by a move made by  $\exists$ loise such that the resulting pointed models are again bisimilar. There are four cases to consider depending on the label of the edge along which  $\forall$ belard moves:

- $\Delta \xrightarrow{@_k} \Delta$  By (atn),  $k^{\mathfrak{M}} B_0 k^{\mathfrak{N}}$ . Also, B is an  $\omega$ -bisimulation between  $(\mathfrak{M}, k^{\mathfrak{M}})$  and  $(\mathfrak{N}, k^{\mathfrak{N}})$ .
- $\Delta \xrightarrow{\langle \mathfrak{a} \rangle} \Delta$  Assume that  $\forall$  belard has chosen  $w' \in \mathfrak{a}^{\mathfrak{M}}(w)$ . By (forth), there exists  $v' \in \mathfrak{a}^{\mathfrak{N}}(v)$  such that  $w' B_0 v'$ . Since B is an  $\omega$ -bisimulation between  $(\mathfrak{M}, w')$  and  $(\mathfrak{N}, v')$ ,  $\exists$  loise can choose v'.
- $\Delta \xrightarrow{\downarrow} \Delta[x]$  The resulting pointed models are  $(\mathfrak{M}^{x \leftarrow w}, w)$  and  $(\mathfrak{N}^{x \leftarrow v}, v)$ . Since  $w \ B_0 \ v$ , by (st), we have  $(w, w) \ B_1 \ (v, v)$ . By Lemma 4.2, there exists an  $\omega$ -bisimulation  $B^x$  between  $(\mathfrak{M}^{x \leftarrow w}, w)$  and  $(\mathfrak{R}^{x \leftarrow v}, v)$ .
- $\Delta \xrightarrow{\exists} \Delta[x]$  Assume  $\forall$  belard has chosen  $w' \in |\mathfrak{M}|$ . Since  $w \ B_0 \ v$ , by (ex-f), there exists  $v' \in |\mathfrak{N}|$  such that  $(w', w) \ B_1 \ (v', v)$ . By Lemma 4.2, there exists an  $\omega$ -bisimulation  $B^x$  between  $(\mathfrak{M}^{x \leftarrow w'}, w)$  and  $(\mathfrak{N}^{x \leftarrow v'}, v)$ . Hence,  $\exists$  loise can choose  $v' \in |\mathfrak{N}|$ .

For the backward implication, for each  $\ell \in \omega$ , we define  $(\overline{\mu}, \mu)$   $B_{\ell}$   $(\overline{\nu}, \nu)$  iff there exists a sequence of moves for the Ehrenfeucht-Fraïssé game as depicted in the following diagram:

Notice that

- $\overline{x}$  is a sequence of  $\ell$  variables and  $\overline{x}(j)$  is the element at position j in  $\overline{x}$  for all  $j \in \{1, \dots, \ell\}$ ;
- $\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}}$  is the unique expansion of  $\mathfrak{M}$  to the signature  $\Delta[\overline{x}]$  interpreting each variable  $\overline{x}(i)$  as the state  $\overline{\mu}(i)$  for all  $i \in \{1, ..., \ell\}$ ;
- $\mathfrak{R}^{\overline{x}\leftarrow\overline{v}}$  is the unique expansion of  $\mathfrak{R}$  to the signature  $\Delta[\overline{x}]$  interpreting each variable  $\overline{x}(i)$  as the state  $\overline{v}(i)$  for all  $i \in \{1, \dots, \ell\}$ ; and
- $(\mathfrak{M}^{\overline{x}\leftarrow\overline{\mu}},\mu)\approx_{\omega}(\mathfrak{N}^{\overline{x}\leftarrow\overline{\nu}},\nu).$

We show that  $B = (B_{\ell})_{\ell \in \omega}$  is an  $\omega$ -bisimulation. Assume that  $(\overline{\mu}, \mu)$   $B_{\ell}$   $(\overline{\nu}, \nu)$ .

- (**prop**) For any propositional symbol  $p \in \text{Prop}$ , since  $(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}}, \mu) \approx_{\omega} (\mathfrak{R}^{\overline{x} \leftarrow \overline{\nu}}, \nu)$ , we have  $p \in M^{\overline{x} \leftarrow \overline{\mu}}(\mu) \iff p \in N^{\overline{x} \leftarrow \overline{\nu}}(\nu)$ . Since  $M^{\overline{x} \leftarrow \overline{\mu}}(\mu) = M(\mu)$  and  $N^{\overline{x} \leftarrow \overline{\nu}}(\nu) = N(\nu)$ , we get  $p \in M(\mu) \iff p \in N(\nu)$ .
- (nom) For any nominal  $k \in F$ , since  $(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}}, \mu) \approx_{\omega} (\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}}, \nu)$ , we have  $k^{(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}})} = \mu \iff k^{(\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}})} = \nu$ . Since  $k^{(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}})} = k^{\mathfrak{M}}$  and  $k^{(\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}})} = k^{\mathfrak{N}}$ , we get  $k^{\mathfrak{M}} = \mu \iff k^{\mathfrak{N}} = \nu$ .
- (wvar) For all indexes  $j \in \{1, \dots, \ell\}$ , since  $(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}}, \mu) \approx_{\omega} (\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}}, \nu)$ , we have  $\overline{x}(j)^{(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}})} = \mu \iff \overline{x}(j)^{(\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}})} = \nu$ . Since  $\overline{x}(j)^{(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}})} = \overline{\mu}(j)$  and  $\overline{x}(j)^{(\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}})} = \overline{\nu}(j)$ , we get  $\overline{\mu}(j) = \mu \iff \overline{\nu}(j) = \nu$ .
- (forth) Let  $\mathfrak{a}$  be an action, and let  $\mu' \in \mathfrak{a}^{\mathfrak{M}}(\mu)$  be a state. Since  $(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}}, \mu) \approx_{\omega} (\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}}, \nu)$ , there exists  $\nu' \in \mathfrak{a}^{\mathfrak{N}}(\nu)$  such that  $(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}}, \mu') \approx_{\omega} (\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}}, \nu')$ . By the definition of  $B_{\ell}$ , we obtain  $(\overline{\mu}, \mu')$   $B_{\ell}(\overline{\nu}, \nu')$ .
- (back) Similar to (forth).

- (st) Since  $(\mathfrak{M}^{\overline{x}\leftarrow\overline{\mu}},\mu) \approx_{\omega} (\mathfrak{R}^{\overline{x}\leftarrow\overline{\nu}},\nu)$ , we get  $(\mathfrak{M}^{\overline{x}x\leftarrow\overline{\mu}\mu},\mu) \approx_{\omega} (\mathfrak{R}^{\overline{x}x\leftarrow\overline{\nu}\nu},\nu)$ , where x is a variable for  $\Delta[\overline{x}]$ . By the definition of  $B_{\ell+1}$ , we obtain  $(\overline{\mu}\mu,\mu)$   $B_{\ell+1}$   $(\overline{\nu}\nu,\nu)$ .
- (ex-f) Let  $\mu' \in |\mathfrak{M}|$ . Since  $(\mathfrak{M}^{\overline{x} \leftarrow \overline{\mu}}, \mu) \approx_{\omega} (\mathfrak{N}^{\overline{x} \leftarrow \overline{\nu}}, \nu)$ , we get  $(\mathfrak{M}^{\overline{x}x \leftarrow \overline{\mu}\mu'}, \mu) \approx_{\omega} (\mathfrak{N}^{\overline{x}x \leftarrow \overline{\nu}\nu'}, \nu)$  for some  $\nu' \in |\mathfrak{N}|$ , where x is a variable for  $\Delta[\overline{x}]$ . By the definition of  $B_{\ell+1}$ , we obtain  $(\overline{\mu}\mu', \mu) B_{\ell+1} (\overline{\nu}\nu', \nu)$ .

## 4.2 Back-and-forth systems and countable EF games

Analogously to Section 4.1, we adapt the notion of back-and-forth system proposed in [3] to our setting, and show that under certain conditions back-and-forth equivalence and the countable EF equivalence ( $\approx_{\omega}$ ) coincide. It turns out however, that in general our back-and-forth equivalence is stronger than  $\omega$ -EF equivalence. Since the conditions we identify here are satisfied in the case considered in [3], this does not contradict Theorem 3.7 and Corollary 3.12 there.

Definition 4.4 (Basic partial isomorphism). Let  $\mathfrak{M}$  and  $\mathfrak{N}$  be two models over a signature  $\Delta$ . A basic partial isomorphism  $h:\mathfrak{M}\to\mathfrak{N}$  is a bijection from a subset of  $|\mathfrak{M}|$  to a subset of  $|\mathfrak{N}|$  such that for all  $w\in \mathrm{dom}(h)$  and all  $\rho\in \mathrm{Sen}_b(\Delta)$  we have

$$(\mathfrak{M}, w) \models \rho$$
 iff  $(\mathfrak{N}, h(w)) \models \rho$ .

The basic partial isomorphism  $g: \mathfrak{M} \to \mathfrak{N}$  extends h, written  $h \subseteq g$ , if  $dom(h) \subseteq dom(g)$  and g(w) = h(w) for all  $w \in dom(h)$ .

A partial isomorphism [3]  $h: \mathfrak{M} \to \mathfrak{N}$  is a basic partial isomorphism such that for all binary relations  $\lambda$  in  $\Delta$  and all states  $w_1, w_2 \in \text{dom}(h)$  we have

$$w_1 \lambda^{\mathfrak{M}} w_2$$
 iff  $h(w_1) \lambda^{\mathfrak{N}} h(w_2)$ .

Since the underlying logic  $\mathcal{L}$  is obtained from HDPL by dropping some of the sentence or action constructors, the following definition is given by cases.

Definition 4.5 (Back-and-forth system). A back-and-forth system between two Kripke structures  $\mathfrak M$  and  $\mathfrak N$  defined over a signature  $\Delta = ((F,P),\mathsf{Prop})$  is a non-empty family I of basic partial isomorphisms between  $\mathfrak M$  and  $\mathfrak N$  satisfying the following properties:

- @-extension If  $\mathcal{L}$  is closed under retrieve, then for all  $h \in \mathcal{I}$  and all  $k \in \mathcal{F}$ , there exists a  $g \in \mathcal{I}$  such that  $h \subseteq g$  and  $k^{\mathfrak{M}} \in \text{dom}(g)$ .
- $\diamond$ -extension If  $\mathcal{L}$  is closed under possibility over an action  $\mathfrak{a}$ , then:

**forth** for all  $h \in I$ , all  $w_1 \in \text{dom}(h)$  and all  $w_2 \in |\mathfrak{M}|$  such that  $w_1 \mathfrak{a}^{\mathfrak{M}} w_2$ , there exists a  $g \in I$  such that  $h \subseteq g$ ,  $w_2 \in \text{dom}(g)$ , and  $g(w_1) \mathfrak{a}^{\mathfrak{M}} g(w_2)$ ;

**back** for all  $h \in I$ , all  $v_1 \in \operatorname{rng}(h)$  and all  $v_2 \in |\mathfrak{N}|$  such that  $v_1 \mathfrak{a}^{\mathfrak{N}} v_2$ , there exists a  $g \in I$  such that  $h \subseteq g$ ,  $v_2 \in \operatorname{rng}(g)$ , and  $g^{-1}(v_1) \mathfrak{a}^{\mathfrak{M}} g^{-1}(v_2)$ .

 $\exists$ **-extension** If  $\mathcal{L}$  is closed under existential quantifiers, then:

**forth** for all  $h \in \mathcal{I}$  and all  $w \in |\mathfrak{M}|$ , there exists a  $g \in \mathcal{I}$  such that  $h \subseteq g$  and  $w \in \text{dom}(g)$ ;

**back** for all  $h \in I$  and all  $v \in |\mathfrak{N}|$ , there exists a  $g \in I$  such that  $h \subseteq g$  and  $v \in \operatorname{rng}(g)$ .

Two Kripke structures  $\mathfrak M$  and  $\mathfrak N$  are back-and-forth equivalent, if there is a back-and-forth system I between  $\mathfrak M$  and  $\mathfrak N$ , in symbols,  $\mathfrak M \equiv_I \mathfrak N$ . Two pointed models  $(\mathfrak M, w)$  and  $(\mathfrak N, v)$  are back-and-forth equivalent, if there is a back-and-forth system I between  $\mathfrak M$  and  $\mathfrak N$  such that h(w) = v for some  $h \in I$ , in symbols,  $(\mathfrak M, w) \equiv_I (\mathfrak N, v)$ .

If  $\mathcal{L}$  is HPL, then the definition of back-and-forth system proposed in this paper is equivalent with the definition of back-and-forth system proposed in [3]:

Lemma 4.6. Assume that  $\diamond \in O$ . Any basic partial isomorphism that belongs to a back-and-forth system is a partial isomorphism.

PROOF. Let h be a basic partial isomorphism belonging to the back-and-forth system I. Let  $w_1, w_2 \in \text{dom}(h)$  such that  $w_1 \lambda^{\mathfrak{M}} w_2$ . Then by the forth  $\langle \lambda \rangle$ -extension, there exists  $g \in I$  such that  $h \subseteq g$  and  $g(w_1) \lambda^{\mathfrak{M}} g(w_2)$ . Since  $g(w_1) = h(w_1)$  and  $g(w_2) = h(w_2)$ , we get  $h(w_1) \lambda^{\mathfrak{M}} h(w_2)$ . For the backward implication, the arguments are the same but we use the back  $\langle \lambda \rangle$ -extension instead of the forth  $\langle \lambda \rangle$ -extension.

In general, back-and-forth equivalence is stronger than the equivalence provided by countably infinite EF games. If  $\mathcal{L}$  satisfies certain closure conditions, back-and-forth equivalence coincides with game equivalence.

Theorem 4.7 (Back-and-forth systems vs. Ehrenfeucht-Fra $\ddot{i}$ ssé games). Let  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  be two pointed models defined over a signature  $\Delta$ .

- (1) If  $(\mathfrak{M}, w) \equiv_{\mathcal{I}} (\mathfrak{N}, v)$  for some back-and-forth system  $\mathcal{I}$ , then  $(\mathfrak{M}, w) \approx_{\omega} (\mathfrak{N}, v)$ .
- (2) Assume that
  - (a)  $\downarrow \in O$ , and
  - (b)  $@ \in O \text{ if } \diamondsuit \in O \text{ or } \exists \in O.$

If  $(\mathfrak{M}, w) \approx_{\omega} (\mathfrak{N}, v)$  then  $(\mathfrak{M}, w) \equiv_{\mathcal{I}} (\mathfrak{N}, v)$  for some back-and-forth system  $\mathcal{I}$ .

PROOF. We prove only the second statement. Assume a sequence of variables  $\overline{z_n} = z_1 \dots z_n$ . Assume two sequences of elements  $\overline{w_n} = w_1 \dots w_n$  and  $\overline{v_n} = v_1 \dots v_n$  from  $\mathfrak{M}$  and  $\mathfrak{N}$ , respectively, such that

$$(\mathfrak{M}^{\overline{z_i} \leftarrow \overline{w_i}}, w_{i+1}) \approx_{\omega} (\mathfrak{N}^{\overline{z_i} \leftarrow \overline{v_i}}, v_{i+1}) \text{ for all } i \in \{1, \dots, n-1\},$$

where  $\overline{z_i} = z_1 \dots z_i$ ,  $\overline{w_i} = w_1 \dots w_i$ , and  $\overline{v_i} = v_1 \dots v_i$ . Since  $\downarrow \in O$ , for each index  $i \in \{1, \dots, n-1\}$ , a move along the edge  $\Delta[\overline{z_i}] \xrightarrow{\downarrow} \Delta[\overline{z_{i+1}}]$  results in  $(\mathfrak{M}^{\overline{z_{i+1}} \leftarrow \overline{w_{i+1}}}, w_{i+1}) \approx_{\omega} (\mathfrak{R}^{\overline{z_{i+1}} \leftarrow \overline{v_{i+1}}}, v_{i+1})$ . Let  $h : \mathfrak{M} \to \mathfrak{R}$  be the basic partial isomorphism defined by  $h(w_i) = v_i$  for all  $i \in \{1, \dots, n\}$ . It is not difficult to show that h is well-defined. Moreover, h can be extended to another basic partial isomorphism  $h \cup \{(w_{n+1}, v_{n+1})\}$  according to Definition 4.5 such that  $(\mathfrak{M}^{\overline{z_{n+1}} \leftarrow \overline{w_{n+1}}}, w_{n+1}) \approx_{\omega} (\mathfrak{R}^{\overline{z_{n+1}} \leftarrow \overline{v_{n+1}}}, v_{n+1})$ .

- @-extension In this case, @  $\in$  O. Let k be any  $\Delta$ -nominal. Let  $w_{n+1} := k^{\mathfrak{M}}$  and  $v_{n+1} := k^{\mathfrak{M}}$ . Consider a move along  $\Delta[\overline{z_n}] \xrightarrow{@_k} \Delta[\overline{z_n}]$ . We get  $(\mathfrak{M}^{\overline{z_n} \leftarrow \overline{w_n}}, w_{n+1}) \approx_{\omega} (\mathfrak{N}^{\overline{z_n} \leftarrow \overline{v_n}}, v_{n+1})$ . Since  $\downarrow \in O$ ,  $(\mathfrak{M}^{\overline{z_{n+1}} \leftarrow \overline{w_{n+1}}}, w_{n+1}) \approx_{\omega} (\mathfrak{N}^{\overline{z_n} \leftarrow \overline{v_n}}, v_{n+1})$ . Let  $g : \mathfrak{M} \to \mathfrak{N}$  be the basic partial isomorphism  $h \cup \{(w_{n+1}, v_{n+1})\}$ .
- $\langle \mathfrak{a} \rangle$ -extension In this case,  $\Diamond \in O$  and  $@ \in O$ . We show that there is a forth  $\Diamond$ -extension of h; for the back  $\Diamond$ -extension, the arguments are symmetric. Assume that  $w_i$   $\mathfrak{a}^{\mathfrak{M}}$   $w_{n+1}$  holds for some  $i \in \{1, \ldots, n\}$ . Consider a move along the edge  $\Delta[\overline{z_n}] \xrightarrow{@z_i} \Delta[\overline{z_n}]$  to obtain  $(\mathfrak{M}^{\overline{z_n} \leftarrow \overline{w_n}}, w_i)$  and  $(\mathfrak{R}^{\overline{z_n} \leftarrow \overline{v_n}}, v_i)$ . Then make another move along  $\Delta[\overline{z_n}] \xrightarrow{\langle \mathfrak{a} \rangle} \Delta[\overline{z_n}]$  to obtain  $(\mathfrak{M}^{\overline{z_n} \leftarrow \overline{w_n}}, w_{n+1}) \approx_{\omega} (\mathfrak{R}^{\overline{z_n} \leftarrow \overline{v_n}}, v_{n+1})$  such that  $v_i$   $\mathfrak{a}^{\mathfrak{R}}$   $v_{n+1}$ . Since  $\downarrow \in O$ ,  $(\mathfrak{M}^{\overline{z_{n+1}} \leftarrow w_{n+1}}, w_{n+1}) \approx_{\omega} (\mathfrak{R}^{\overline{z_{n+1}} \leftarrow \overline{v_{n+1}}}, v_{n+1})$ . Let  $g : \mathfrak{M} \to \mathfrak{R}$  be the basic partial isomorphism  $h \cup \{(w_{n+1}, v_{n+1})\}$ .
- $\exists$ -extension In this case,  $\exists \in O$  and  $\textcircled{o} \in O$ . We show that there exists a forth  $\exists$ -extension of h; for the back  $\exists$ -extension, the arguments are symmetric. Let  $w_{n+1}$  be any state from  $\mathfrak{M}$ . Let us consider a move along the edge  $\Delta[\overline{z_n}] \xrightarrow{\exists} \Delta[\overline{z_{n+1}}]$ . We get  $(\mathfrak{M}^{\overline{z_{n+1}}} \leftarrow \overline{w_{n+1}}, w_n) \approx_{\omega} (\mathfrak{N}^{\overline{w_{n+1}}} \leftarrow \overline{v_{n+1}}, v_n)$ . Then make another move along  $\Delta[\overline{z_{n+1}}] \xrightarrow{\textcircled{o}z_{n+1}} \Delta[\overline{z_{n+1}}]$ . It follows that  $(\mathfrak{M}^{\overline{z_{n+1}}} \leftarrow \overline{w_{n+1}}, w_{n+1}) \approx_{\omega} (\mathfrak{N}^{\overline{z_{n+1}}} \leftarrow \overline{v_{n+1}}, v_{n+1})$ . Let  $g: \mathfrak{M} \to \mathfrak{N}$  be the basic partial isomorphism  $h \cup \{(w_{n+1}, v_{n+1})\}$ .

One can start with two pointed models  $(\mathfrak{M}, w_1)$  and  $(\mathfrak{N}, v_1)$  such that  $(\mathfrak{M}, w_1) \approx_{\omega} (\mathfrak{N}, v_1)$ , define a basic partial isomorphism  $h: \mathfrak{M} \to \mathfrak{N}$  by  $h(w_1) = v_1$  and then extend it as described above to build a back-and-forth system I between  $\mathfrak{M}$  and  $\mathfrak{N}$ .

Note that Theorem 4.7(1) applies to HDPL, HPL and DPL, while Theorem 4.7(2) applies to HDPL and HPL but not to DPL (since it requires closure under store).

The following example shows that the assumption on closure under retrieve in presence of possibility is necessary for Theorem 4.7(2).

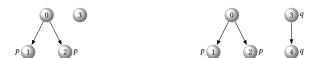
*Example 4.8.* Let  $\Delta$  be a signature with no nominals, one binary relation symbol  $\lambda$  and one propositional symbol p. Let  $\mathfrak M$  and  $\mathfrak N$  be the  $\Delta$ -models shown to the left and right, respectively, in the following diagram.



If  $\mathcal{L}$  is obtained from HDPL by dropping @ and  $\exists$ , then it is straightforward to show that  $(\mathfrak{M},0) \approx_{\omega} (\mathfrak{N},0)$ . Now let  $h: \mathfrak{M} \to \mathfrak{N}$  be the basic partial isomorphism defined by h(0) = 0 and h(1) = 1. Then there is no forth  $\diamondsuit$ -extension of h to 2. Therefore, there is no back-and-forth system between  $\mathfrak{M}$  and  $\mathfrak{N}$ .

The following example shows that the assumption on closure under retrieve in the presence of existential quantifiers is necessary for Theorem 4.7(2).

*Example 4.9.* Let  $\Delta$  be a signature with no nominals, one binary relation symbol  $\lambda$  and two propositional symbols  $\{p,q\}$ . Let  $\mathfrak{M}$  and  $\mathfrak{N}$  be the  $\Delta$ -models shown to the left and right, respectively, in the following diagram.



If  $\mathcal{L}$  is obtained from HDPL by dropping @, then  $(\mathfrak{M},0) \approx_{\omega} (\mathfrak{N},0)$  because the current state will always be in the connected component of 0 during the EF game (regardless of whether the state 3 is named or not,  $\forall$ belard cannot change the current state to 3 in the absence of retrieve). Now, assume a basic partial isomorphism  $h: \mathfrak{M} \to \mathfrak{N}$  defined by h(i) = i for all  $i \in \{0, \dots, 2\}$ . There is no forth  $\exists$ -extension of h to 3. Therefore, there is no back-and-forth system between  $\mathfrak{M}$  and  $\mathfrak{N}$ .

# 4.3 Image-finite models and the Hennessy-Milner theorem

The main result of this section is a Hennessy-Milner theorem. Here, and indeed for the remainder of the paper, we drop the first-order quantifiers and the constructors for actions. Thus, we work within a quantifier-free fragment of HPL closed under possibility, that is,  $\diamond \in O$ .

Definition 4.10 (Image-finite model). A model  $\mathfrak{M}$  is image-finite if each state has a finite number of direct successors, that is,  $\lambda^{\mathfrak{M}}(w)$  is finite for all states w in  $\mathfrak{M}$  and all binary relation symbols  $\lambda$  in the underlying signature. A pointed model  $(\mathfrak{M}, w)$  is image-finite if  $\mathfrak{M}$  is image-finite.

We show that two image finite pointed models  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  are elementarily equivalent iff they are game equivalent w.r.t. all  $\omega$ -EF games.

Theorem 4.11. Let  $(\mathfrak{M}, w)$  and  $(\mathfrak{R}, v)$  be two image-finite pointed models defined over a signature  $\Delta$ . Then:

$$(\mathfrak{M}, w) \equiv (\mathfrak{N}, v)$$
 iff  $(\mathfrak{M}, w) \approx_{\omega} (\mathfrak{N}, v)$ .

PROOF. For the backward implication, assume that  $(\mathfrak{M}, w) \approx_{\omega} (\mathfrak{N}, v)$ . Since all sentences are of finite length,

$$(\mathfrak{M}, w) \equiv (\mathfrak{N}, v)$$
 iff  $(\mathfrak{M}|_{\Delta_f}, w) \equiv (\mathfrak{N}|_{\Delta_f}, v)$  for all finite signatures  $\Delta_f \subseteq \Delta$ . (1)

For all finite signatures  $\Delta_f \subseteq \Delta$ , since  $(\mathfrak{M}, w) \approx_{\omega} (\mathfrak{N}, v)$ , we have  $(\mathfrak{M}|_{\Delta_f}, w) \approx_{\omega} (\mathfrak{N}|_{\Delta_f}, v)$ , which implies  $(\mathfrak{M}|_{\Delta_f}, w) \approx_{tr} (\mathfrak{N}|_{\Delta_f}, v)$  for all gameboard trees tr; by Corollary 3.7, we obtain  $(\mathfrak{M}|_{\Delta_f}, w) \equiv (\mathfrak{N}|_{\Delta_f}, v)$ . By (1), we get  $(\mathfrak{M}, w) \equiv (\mathfrak{N}, v)$ . For the forward implication, first, we show that for all binary relations symbols  $\lambda$  in  $\Delta$  and all states  $w' \in \lambda^{\mathfrak{M}}(w)$ , there exists a state  $v' \in \lambda^{\mathfrak{M}}(v)$  such that  $(\mathfrak{M}, w') \equiv (\mathfrak{N}, v')$ . Assume that  $\lambda^{\mathfrak{N}}(v) = \{v_1, \dots, v_n\}$  and let  $w_1 \in \lambda^{\mathfrak{M}}(w)$ . Suppose towards a contradiction that for each  $i \in \{1, \dots, n\}$  there exists a sentence  $\phi_i$  such that  $(\mathfrak{M}, w_1) \models \phi_i$  and  $(\mathfrak{N}, v_i) \not\models \phi_i$ . We have  $(\mathfrak{M}, w) \models \langle \lambda \rangle \phi_1 \wedge \dots \wedge \phi_n$  but  $(\mathfrak{N}, v) \not\models \langle \lambda \rangle \phi_1 \wedge \dots \wedge \phi_n$ , which is a contradiction with our assumptions. Therefore, there exists  $i \in \{1, \dots, n\}$  such that for all sentences  $\phi$ , we have  $(\mathfrak{M}, w_1) \models \phi$  iff  $(\mathfrak{N}, v_i) \models \phi$ , that is,  $(\mathfrak{M}, w_1) \equiv (\mathfrak{N}, v_i)$ .

Secondly, we show that  $\exists$  loise has a winning strategy for the EF game played over a complete gameboard tree  $tr = \Delta(\xrightarrow{lb_1} tr_1, \xrightarrow{lb_2} tr_2, \ldots)$  of height  $\omega$ . Assume that  $\forall$  belard moves along an edge  $\Delta \xrightarrow{lb_i} tr_i$ . We will show that  $\exists$  loise can match  $\forall$  belard's move such that the resulting pair of pointed models are elementarily equivalent. Depending on the label  $lb_i$ , we have three non-trivial cases:

- $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  Assume that  $\forall$  belard's move along  $\Delta \xrightarrow{\langle \lambda \rangle} tr_i$  is  $(\mathfrak{M}, w_i)$  where  $w_i \in \lambda^{\mathfrak{M}}(w)$ . By the first part of the proof, there exists  $v_i \in \lambda^{\mathfrak{N}}(v)$  such that  $(\mathfrak{M}, w_i) \equiv (\mathfrak{N}, v_i)$ .
- $\Delta \xrightarrow{@k} \Delta$  A move along this edge means that  $\forall$  belard's pair becomes  $(\mathfrak{M}, k^{\mathfrak{M}})$  and  $\exists$  loise's pair becomes  $(\mathfrak{N}, k^{\mathfrak{N}})$ . Since  $(\mathfrak{M}, w) \equiv (\mathfrak{N}, v)$ , we get  $(\mathfrak{M}, k^{\mathfrak{M}}) \equiv (\mathfrak{N}, k^{\mathfrak{N}})$ .
- $\Delta \xrightarrow{\downarrow} \Delta[x]$  A move along this edge means that the new pair of pointed models consists of  $(\mathfrak{M}^{x\leftarrow w}, w)$  and  $(\mathfrak{R}^{x\leftarrow v}, v)$ . This move gives name x to the states w and v. For all  $\Delta[x]$ -sentences  $\phi$ , we have  $(\mathfrak{M}^{x\leftarrow w}, w) \models \phi$  iff  $(\mathfrak{M}, w) \models \downarrow x \cdot \phi$  iff  $(\mathfrak{M}, w) \models \downarrow x \cdot \phi$  iff  $(\mathfrak{M}^{x\leftarrow v}, v) \models \phi$ . Therefore,  $(\mathfrak{M}^{x\leftarrow w}, w) \equiv (\mathfrak{R}^{x\leftarrow v}, v)$ .

In all three cases,  $tr_i$  is a gameboard tree and the pointed models obtained are elementarily equivalent. In particular, the resulting pointed models satisfy the same basic sentences. It follows that  $(\mathfrak{M}, w) \approx_{tr} (\mathfrak{N}, v)$ . Hence,  $(\mathfrak{M}, w) \approx_{\omega} (\mathfrak{N}, v)$ 

Image-finiteness is indeed necessary. Recall the models  $\mathfrak M$  and  $\mathfrak N$  from Example 3.2.



 $(\mathfrak{M}, 0)$  and  $(\mathfrak{N}, 0)$  are elementarily equivalent, but they are not  $\omega$ -game equivalent.  $\forall$ belard can win the EF game played over a complete gameboard tree of height  $\omega$ .  $\forall$ belard's moves are depicted in the following diagram.

First,  $\forall$  belard moves  $(\mathfrak{R},0)$  along  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  to obtain  $(\mathfrak{R},1)$ . A move from  $\exists$  loise results in  $(\mathfrak{M},n1)$ , where n is a natural number greater than 0. Then  $\forall$  belard moves (n-1)-times the pointed model  $(\mathfrak{R},1)$  along  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  to obtain  $(\mathfrak{R},n)$ .  $\exists$  loise can move (n-1)-times the pointed model  $(\mathfrak{M},n1)$  along  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  to get  $(\mathfrak{M},nn)$ . For the final round,  $\forall$  belard takes  $(\mathfrak{R},n)$  along  $\Delta \xrightarrow{\langle \lambda \rangle} \Delta$  to obtain  $(\mathfrak{R},n+1)$  while  $\exists$  loise cannot match this move.

The following result is a corollary of Theorem 4.3 and Theorem 4.11.

COROLLARY 4.12 (HENNESSY-MILNER THEOREM). Let  $(\mathfrak{M}, w)$  and  $(\mathfrak{N}, v)$  be two image-finite pointed models. Then:

$$(\mathfrak{M}, w) \equiv (\mathfrak{N}, v)$$
 iff  $(\mathfrak{M}, w) \equiv_B (\mathfrak{N}, v)$ .

LEMMA 4.13. Assume that  $\{\diamondsuit, @, \downarrow\} \subseteq O$ . Let  $\mathfrak{M}$  and  $\mathfrak{N}$  be two Kripke structures defined over a signature  $\Delta$ . Let B an  $\omega$ -bisimulation between  $\mathfrak{M}$  and  $\mathfrak{N}$  such that  $(\overline{w}, w)$   $B_{\ell}$   $(\overline{v}, v)$ . Then  $h: \mathfrak{M} \to \mathfrak{N}$  defined by  $h(\overline{w}(i)) = \overline{v}(i)$  for all  $i \in \{1, \ldots, \ell\}$  is a partial isomorphism.

PROOF. Let  $i, j \in \{1, ..., \ell\}$  be two arbitrary natural numbers. Since  $(\overline{w}, w)$   $B_{\ell}(\overline{v}, v)$ , by (atv),  $(\overline{w}, \overline{w}(i))$   $B_{\ell}(\overline{v}, \overline{v}(i))$ .

- By (wvar),  $\overline{w}(i) = \overline{w}(j)$  iff  $\overline{v}(i) = \overline{v}(j)$ . Hence, h is a partial bijection.
- By (prop) and (nom),  $(\mathfrak{M}, \overline{w}(i)) \models \rho$  iff  $(\mathfrak{N}, \overline{v}(i)) \models \rho$  for all  $\rho \in \mathsf{Sen}_b(\Delta)$ .
- If  $\overline{w}(i) \lambda^{\mathfrak{M}} \overline{w}(j)$  then since  $(\overline{w}, \overline{w}(i)) B_{\ell}(\overline{v}, \overline{v}(i))$ , by (forth),  $(\overline{w}, \overline{w}(j)) B_{\ell}(\overline{v}, v')$  for some state  $v' \in \lambda^{\mathfrak{N}}(\overline{v}(i))$ ; by (wvar),  $v' = \overline{v}(j)$ , which means  $\overline{v}(i) \lambda^{\mathfrak{N}} \overline{v}(j)$ .

  Similarly, if  $\overline{v}(i) \lambda^{\mathfrak{N}} \overline{v}(j)$  then by (back) and (wvar),  $\overline{w}(i) \lambda^{\mathfrak{M}} \overline{w}(j)$ .

Definition 4.14 (Rooted pointed model). A pointed model  $(\mathfrak{M}, w)$  defined over a signature  $\Delta = ((F, P), \mathsf{Prop})$  is rooted if  $v \in (\bigcup_{\lambda \in P} \lambda^{\mathfrak{M}})^*(w)$  for all possible worlds  $v \in |\mathfrak{M}|$ .

THEOREM 4.15. Assume that  $\{\diamondsuit, @, \downarrow\} \subseteq O$ . Let  $(\mathfrak{M}, w_0)$  and  $(\mathfrak{N}, v_0)$  be two rooted pointed models that are countable. Then:

$$(\mathfrak{M}, w_0) \cong (\mathfrak{N}, v_0)$$
 iff  $(\mathfrak{M}, w_0) \equiv_B (\mathfrak{N}, v_0)$ .

PROOF. Obviously, any isomorphic pointed models are  $\omega$ -bisimilar. For the backward implication, let  $\{w_i \mid i < \omega\}$  and  $\{v_i \mid i < \omega\}$  be enumerations of all possible worlds of  $\mathfrak{M}$  and  $\mathfrak{N}$ , respectively, such that  $w_i$  and  $v_i$  are the direct successor of some state in  $W_i = \{w_j \mid j < i\}$  and  $V_i = \{v_j \mid j < i\}$ , respectively, for all ordinals  $i < \omega$ . We define a family of bisimilar correspondences  $\{(\overline{\mu_\ell}, \mu_\ell) \mid B_\ell (\overline{\nu_\ell}, \nu_\ell) \mid \ell \in \omega\}$  by induction:

- $(\ell = 0)$  We have  $w_0 B_0 v_0$ . Let  $\mu_0 := w_0$  and  $v_0 := v_0$ .
- $(2\ell \Rightarrow 2\ell + 1)$  We assume that  $(\overline{\mu_{2\ell}}, \mu_{2\ell})$   $B_{2\ell}$   $(\overline{\nu_{2\ell}}, \nu_{2\ell})$  is defined such that
  - (1)  $w_j$  is in the sequence  $\overline{\mu_{2\ell}} \mu_{2\ell}$  for all  $j \in \{0, ..., \ell\}$ , and
  - (2)  $v_j$  is in the sequence  $\overline{v_{2\ell}} v_{2\ell}$  for all  $j \in \{0, \dots, \ell\}$ .

By (st), we get  $(\overline{\mu_{2\ell}} \mu_{2\ell}, \mu_{2\ell})$   $B_{2\ell+1}$   $(\overline{v_{2\ell}} v_{2\ell}, v_{2\ell})$ . The goal is to add  $w_{\ell+1}$  to the bisimilar correspondence. Let  $\overline{\mu_{2\ell+1}} := \overline{\mu_{2\ell}} \mu_{2\ell}$  and  $\overline{v_{2\ell+1}} := \overline{v_{2\ell}} v_{2\ell}$ . Notice that  $w_{\ell+1}$  is a successor of some state  $w_j \in W_{\ell+1}$ , which is included in the sequence  $\overline{\mu_{2\ell+1}}$ . Therefore,  $w_j = \overline{\mu_{2\ell+1}}(i)$  for some  $i \in \{1, \ldots, 2\ell+1\}$ . By (atv),  $(\overline{\mu_{2\ell+1}}, \overline{\mu_{2\ell+1}}(i))$   $B_{2\ell+1}$   $(\overline{v_{2\ell+1}}, \overline{v_{2\ell+1}}(i))$ . By (forth),  $(\overline{\mu_{2\ell+1}}, w_{\ell+1})$   $B_{2\ell+1}$   $(\overline{v_{2\ell+1}}, v_{2\ell+1})$ . Let  $\mu_{2\ell+1} := w_{\ell+1}$ .

 $(2\ell+1\Rightarrow 2\ell+2)$  By (st), we get  $(\overline{\mu_{2\ell+1}}\,\mu_{2\ell+1},\mu_{2\ell+1})$   $B_{2\ell+2}$   $(\overline{v_{2\ell+1}}\,v_{2\ell+1},v_{2\ell+1})$ . The goal is to add  $v_{\ell+1}$  to the bisimilar correspondence. Let  $\overline{\mu_{2\ell+2}} := \overline{\mu_{2\ell+1}}\,\mu_{2\ell+1}$  and  $\overline{v_{2\ell+2}} := \overline{v_{2\ell+1}}\,v_{2\ell+1}$ . Notice that  $v_{\ell+1}$  is a successor of some state  $v_j$  in  $V_{\ell+1}$ , which is included in the sequence  $\overline{v_{2\ell+2}}$ . Therefore,  $v_j = \overline{v_{2\ell+2}}(i)$  for some  $i \in \{1, \dots, 2\ell+2\}$ .

By (atv), we get  $(\overline{\mu_{2\ell+2}}, \overline{\mu_{2\ell+2}}(i))$   $B_{2\ell+2}$   $(\overline{\nu_{2\ell+2}}, \overline{\nu_{2\ell+2}}(i))$ . By (back),  $(\overline{\mu_{2\ell+2}}, \mu_{2\ell+2})$   $B_{2\ell+2}$   $(\overline{\nu_{2\ell+2}}, v_{\ell+1})$ . Let  $v_{2\ell+2} := v_{\ell+1}$ .

By Lemma 4.13, for each  $\ell \in \omega$ ,  $h_{\ell} : \mathfrak{M} \to \mathfrak{N}$  defined by  $h_{\ell}(\overline{\mu_{\ell}}(i)) = \overline{v_{\ell}}(i)$  for all  $i \in \{1, ..., \ell\}$  is a partial isomorphism. Since for all  $\ell \in \omega$ ,  $\operatorname{dom}(h_{\ell}) \subseteq \operatorname{dom}(h_{\ell+1})$ , the union  $h = \bigcup_{\ell \in \omega} h_{\ell}$  is well-defined and it is a partial isomorphism. Since for all  $\ell \in \omega$ ,  $w_{\ell} \in \operatorname{dom}(h_{2\ell})$  and  $v_{\ell} \in \operatorname{dom}(h_{2\ell+1})$ , h is an isomorphism.

The following result is a consequence of Corollary 4.12 and Theorem 4.15.

COROLLARY 4.16. Assume that  $\{\diamondsuit, @, \downarrow\} \subseteq O$ . Let  $(\mathfrak{M}, w_0)$  and  $(\mathfrak{N}, v_0)$  be two rooted image-finite pointed models. Then:

$$(\mathfrak{M}, w_0) \cong (\mathfrak{N}, v_0)$$
 iff  $(\mathfrak{M}, w_0) \equiv (\mathfrak{N}, v_0)$ .

Notice that Theorem 4.15 and Corollary 4.12 hold also in HDPL, since both elementary equivalence and  $\omega$ -bisimulation are stronger in HDPL than in HPL.

# 5 CONCLUSIONS AND FUTURE WORK

We presented a novel notion of EF games for hybrid-dynamic propositional logic and its fragments. Gameboard trees were introduced out of necessity when seeking a solution to accommodate moves in hybrid-dynamic EF games corresponding to different types of quantification. The best solution we could find (likely the cleanest and most elegant) was based on gameboard trees. Hybrid-dynamic EF games utilizing gameboard trees are applicable to other types of quantification, such as those related to temporal operators studied in [16]. Via gameboard sentences, the finite hybrid-dynamic EF games thus capture elementary equivalence and characterize their corresponding language fragment precisely. We showed that the existence of a winning strategy for the countably infinite EF game coincides with the existence of an  $\omega$ -bisimulation and, under certain conditions, a back-and-forth system between the structures. The parametric, syntactic approach of designing the moves in hybrid-dynamic EF games should be applicable also to other variants of hybrid-dynamic logic, like its integration with branching-time logics [16] or with past operators [1] or rigid symbols [11, 12]. A future direction of research involves generalizing the current approach to EF games to an institutional setting, utilizing category theory, as exemplified in [13]. The institution-independent framework could be instantiated for other hybrid-dynamic logics such as Hybrid-Dynamic First-Order Logic with rigid symbols [12] or Hybrid-Dynamic First-Order Logic with user-defined sharing. The hybrid counterpart of the latter logic [9] serves as the underlying logic of the H tool; refer to [6] for further details.

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